The **OpenCL** C++ Wrapper API

*Version: 1.2*

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Khronos OpenCL Working Group

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1. Introduction

This specification describes the OpenCL C++ wrapper API (Version 1.2). It should be used in conjunction with the OpenCL Specification, Version 1.2. The C++ wrapper is built on top of the OpenCL C API and is not a replacement for it. An implementation of the C++ Wrapper API calls the underlying C API, which is assumed to be a compliant implementation of the OpenCL Specification platform and runtime API. The C++ API corresponds closely to the underlying C API and introduces no additional execution overhead.

The wrapper interface is defined within a single C++ header file cl.hpp. All its definitions are contained within namespace cl. There is no additional requirement to include cl.h; to use either the C++ wrapper or the original C API, simply include cl.hpp.

The API is divided into a number of classes with corresponding OpenCL C types. For example, class cl::Memory maps to OpenCL type cl_mem. When possible, C++ inheritance provides an extra level of type correctness and abstraction. For example, class cl::Buffer derives from base class cl::Memory but represents the 1D memory subclass of all possible OpenCL memory objects.

The following sections describe each class in detail. The index section at the end of this document lists each class, constructor, and method defined by the C++ wrapper API.

2. C++ Platform layer

2.1 Platforms

Class cl::Platform provides functionality for working with OpenCL platforms. The following static method lists the available platforms:

```cpp
static cl_int cl::Platform::get(VECTOR_CLASS<Platform> * platforms)
```

The method `cl::Platform::get` returns CL_SUCCESS on success. Otherwise, it returns the following error:

- CL_INVALID_VALUE if `platforms` is NULL.

The method

```cpp
cl_int cl::Platform::getInfo(cl_platform_info name,
                          STRING_CLASS * param)
```

---

1 Section 5 describes C++ classes VECTOR_CLASS and STRING_CLASS.
gets specific information about the OpenCL platform. Table 4.1 of the *OpenCL Specification* Version 1.2 specifies the information that can be queried. The table below lists `cl_platform_info` values that differ in return type between the OpenCL C API and the OpenCL C++ API.

<table>
<thead>
<tr>
<th>cl_platform_info</th>
<th>C++ return Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_PLATFORM_EXTENSIONS</td>
<td>STRING_CLASS</td>
</tr>
<tr>
<td>CL_PLATFORM_NAME</td>
<td>STRING_CLASS</td>
</tr>
<tr>
<td>CL_PLATFORM_PROFILE</td>
<td>STRING_CLASS</td>
</tr>
<tr>
<td>CL_PLATFORM_VENDOR</td>
<td>STRING_CLASS</td>
</tr>
<tr>
<td>CL_PLATFORM_VERSION</td>
<td>STRING_CLASS</td>
</tr>
</tbody>
</table>

Table 1: Differences in `cl::Platform::getInfo` return type vs. *OpenCL Specification* table 4.1

`name` is an enumeration constant that identifies the platform information being queried. It can be one of the values specified in table 4.1.

`param` is a pointer to a memory location where the appropriate values for a given `name` as specified in table 4.1 is returned. If `param` is NULL, it is ignored.

`cl::Platform::getInfo` returns CL_SUCCESS on success. Otherwise, it returns:
- CL_INVALID_VALUE if `name` is not one of the supported values.

The method

```cpp
template <cl_int name> typename
detail::param_traits<detail::cl_platform_info, name>::param_type
cl::Platform::getInfo (void)
```

gets specific information about the OpenCL platform. Table 4.1 of the *OpenCL Specification* Version 1.2 specifies the information that can be queried. The table above lists `cl_platform_info` values that differ in return type between the OpenCL C API and the OpenCL C++ API.

`name` is an enumeration constant that identifies the platform information being queried. It can be one of the values specified in table 4.1.

`cl::Platform::getInfo` returns the appropriate value for a given `name` as specified in table 4.1.

The method

```cpp
cl_int cl::Platform::getDevices(cl_device_type type,
                                VECTOR_CLASS<Device> * devices)
```

gets the list of devices available on a platform.

`type` is a bitfield that identifies OpenCL device type. The `type` can be used to query specific OpenCL devices or all available OpenCL devices. Table 4.2 of the *OpenCL Specification* Version 1.2 specifies the valid values for `type`.

`devices` returns a vector of OpenCL devices found. If `devices` is NULL, it is ignored.


cl::Platform::getDevices returns CL_SUCCESS if the method is executed successfully. Otherwise, it returns one of the following errors:

- CL_INVALID_DEVICE_TYPE if type is not a valid value.
- CL_DEVICE_NOT_FOUND if no OpenCL devices matching type were found.

## 2.2 Devices

Class cl::Device provides functionality for working with OpenCL devices.

The constructor

```cpp
cl::Device::Device(cl_device_id * device)
```

creates an OpenCL device wrapper for a device.

*device* is an OpenCL device id.

The method

```cpp
template <typename T>
cl_int cl::Device::getInfo(cl_device_info name,
T * param)
```

gets specific information about the OpenCL device. Table 4.3 of the *OpenCL Specification* Version 1.2 specifies the information that can be queried. The table below lists cl_device_info values that differ in return type between the OpenCL C API and the OpenCL C++ API.

<table>
<thead>
<tr>
<th>cl_device_info</th>
<th>C++ return Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_DEVICE_BUILT_IN_KERNELS</td>
<td>STRING_CLASS</td>
</tr>
<tr>
<td>CL_DEVICE_EXTENSIONS</td>
<td>STRING_CLASS</td>
</tr>
<tr>
<td>CL_DEVICE_MAX_WORK_ITEM_SIZES</td>
<td>VECTOR_CLASS&lt;&lt;size_t&gt;</td>
</tr>
<tr>
<td>CL_DEVICE_NAME</td>
<td>STRING_CLASS</td>
</tr>
<tr>
<td>CL_DEVICE_OPENCL_C_VERSION</td>
<td>STRING_CLASS</td>
</tr>
<tr>
<td>CL_DEVICE_PARTITION_PROPERTIES</td>
<td>VECTOR_CLASS&lt;cl_device_partition_property&gt;</td>
</tr>
<tr>
<td>CL_DEVICE_PARTITION_TYPE</td>
<td>VECTOR_CLASS&lt;cl_device_partition_property&gt;</td>
</tr>
<tr>
<td>CL_DEVICE_PROFILE</td>
<td>STRING_CLASS</td>
</tr>
<tr>
<td>CL_DEVICE_VENDOR</td>
<td>STRING_CLASS</td>
</tr>
<tr>
<td>CL_DEVICE_VERSION</td>
<td>STRING_CLASS</td>
</tr>
<tr>
<td>CL_DRIVER_VERSION</td>
<td>STRING_CLASS</td>
</tr>
</tbody>
</table>

*Table 2: Differences in cl::Context::getInfo return type vs. OpenCL Specification table 4.3*

*T* is a compile time argument that is the return for the specific information being queried. It corresponds to the values in table 4.3.

*name* is an enumeration constant that identifies the device information being queried. It can be one of the values specified in table 4.3.
param is a pointer to a memory location where the appropriate values for a given name as specified in table 4.3 is returned. If param is NULL, it is ignored.

cl::Device::getInfo returns CL_SUCCESS on success. Otherwise, it returns:
- CL_INVALID_VALUE if name is not one of the supported values.

The method

```cpp
template <cl_int name> typename detail::param_traits<detail::cl_device_info, name>::param_type
cl::Device::getInfo(void)
```

gets specific information about the OpenCL device. Table 4.3 specifies the information that can be queried.

name is an enumeration constant that identifies the device information being queried. It can be one of the values specified in table 4.3.

cl::device::getInfo returns the appropriate value for a given name as specified in table 4.3 in conjunction with the table above.

The method

```cpp
cl_int cl::Device::createSubDevices(const cl_device_partition_property *properties,
    VECTOR_CLASS<Device>* devices)
```

creates an array of sub-devices that each reference a non-intersecting set of compute units of an OpenCL device.

properties specifies how to partition the device. Each property should be an enumeration constant as specified in table 4.4 of the OpenCL Specification Version 1.2.

devices is a buffer where the OpenCL sub-devices is returned. If devices is null, this argument is ignored.

cl::Device::createSubDevices returns CL_SUCCESS if the method is executed successfully.

## 2.3 Contexts

Class cl::Context provides functionality for working with OpenCL contexts.

The constructor

```cpp
cl::Context::Context(VECTOR_CLASS<Device>& devices,
    cl_context_properties * properties = NULL,
    void (CL_CALLBACK * pfn_notify)(
        const char * errorinfo,
        const void * private_info,
        ::size_t cb,
        void * user_data) = NULL,
    void * user_data = NULL,
    cl_int * err = NULL)
```
creates an OpenCL context.

*devices* is a pointer to a vector of unique devices returned by `cl::Platform::getDevices`. If more than one device is specified, a selection criteria may be applied to determine if the list of devices specified can be used together to create a context.

*properties* specifies a list of context property names and their corresponding values. Each property name is immediately followed by the corresponding desired value. The list is terminated with 0. The list of supported properties is described in table 4.5 of the OpenCL Specification. *properties* can be NULL, in which case the platform that is selected is implementation-defined.

*pfn_notify* is a callback function registered by the application. This callback function is used by the OpenCL implementation to report information on errors that occur in this context. This callback function may be called asynchronously by the OpenCL implementation. It is the application’s responsibility to ensure that the callback function is thread-safe. The parameters to the callback function are:

- *errinfo* is a pointer to an error string.
- *private_info* and *cb* represent a pointer to binary data returned by the OpenCL implementation that can be used to log additional information helpful in debugging the error.
- *user_data* is a pointer to user supplied data.

If *pfn_notify* is NULL, no callback function is registered.

*user_data* is passed as the *user_data* argument when *pfn_notify* is called. *user_data* can be NULL.

*err* returns an appropriate error code. If *err* is NULL, no error code is returned.

`cl::Context::Context` returns a valid object of type `cl::Context` and sets *err* to `CL_SUCCESS` if it creates the context successfully. Otherwise, it returns one of the following error values in *err*:

- CL_INVALID_PROPERTY if context property name in properties is not a supported property name, if the value specified for a supported property name is not valid, or if the same property name is specified more than once.
- CL_INVALID_VALUE if *devices* is of length zero.
- CL_INVALID_VALUE if *pfn_notify* is NULL but *user_data* is not NULL.
- CL_INVALID_DEVICE if *devices* contains an invalid device.
- CL_DEVICE_NOT_AVAILABLE if a device in *devices* is currently not available even though the device was returned by `cl::Platform::getDevices`.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The constructor

```cpp
cl::Context::Context(cl_device_type type,
    cl_context_properties *properties = NULL,
    void (CL_CALLBACK *pfn_notify)(
        const char *errorinfo,
        const void *private_info,
        ::size_t cb,
        void *user_data) = NULL,
```
void * user_data = NULL,
cl_int * err = NULL)

creates an OpenCL context from a device type that identifies the specific devices to use.

type is a bit-field that identifies the type of device, as described in table 4.2 in section 4.2 of the OpenCL Specification Version 1.2.

properties specifies a list of context property names and their corresponding values. Each property name is immediately followed by the corresponding desired value. The list is terminated with 0. The list of supported properties is described in table 4.4. properties can be NULL, in which case the platform that is selected is implementation-defined.

pfn_notify is a callback function registered by the application. This callback function is used by the OpenCL implementation to report information on errors that occur in this context. This callback function may be called asynchronously by the OpenCL implementation. It is the application’s responsibility to ensure that the callback function is thread-safe. The parameters to the callback function are:

- errinfo is a pointer to an error string.
- private_info and cb represent a pointer to binary data that is returned by the OpenCL implementation that can be used to log additional information helpful in debugging the error.
- user_data is a pointer to user supplied data.

If pfn_notify is NULL, no callback function is registered.

user_data is passed as the user_data argument when pfn_notify is called. user_data can be NULL.

err returns an appropriate error code. If err is NULL, no error code is returned.

cl::Context::Context returns a valid object of type cl::Context and sets err to CL_SUCCESS if it creates the context successfully. Otherwise, it returns one of the following error values in err:

- CL_INVALID_PROPERTY if context property name in properties is not a supported property name, if the value specified for a supported property name is not valid, or if the same property name is specified more than once.
- CL_INVALID_VALUE if pfn_notify is NULL but user_data is not NULL.
- CL_INVALID_DEVICE_TYPE if type is not a valid value.
- CL_DEVICE_NOT_AVAILABLE if no devices that match type and property values specified in properties are currently available.
- CL_DEVICE_NOT_FOUND if no devices that match type and property values specified in properties were found.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The method

template <typename T>
cl_int cl::Context::getInfo(cl_context_info name,
                             T * param)
gets specific information about the OpenCL context. Table 4.6 of the *OpenCL Specification* Version 1.2 specifies the information that can be queried. The table below lists `cl_context_info` values that differ in return type between the OpenCL C API and the OpenCL C++ API.

<table>
<thead>
<tr>
<th>cl_context_info</th>
<th>C++ return Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_CONTEXT_DEVICES</td>
<td>VECTOR_CLASS<a href="">cl::Device</a></td>
</tr>
<tr>
<td>CL_CONTEXT_PROPERTIES</td>
<td>VECTOR_CLASS&lt;cl_context_properties&gt;</td>
</tr>
</tbody>
</table>

Table 3: Differences in cl::Context::getInfo return type vs. OpenCL Specification table 4.6

\( T \) is a compile time argument that is the return type for the specific information being queried. It corresponds to the values in tables 4.6.

\( name \) is an enumeration constant that identifies the context information being queried. It can be one of the values specified in table 4.6.

\( param \) is a pointer to a memory location where the appropriate values for a given \( name \) as specified in table 4.5 is returned. If \( param \) is NULL, it is ignored.

**cl::Context::getInfo** returns CL_SUCCESS on success. Otherwise, it returns:
- CL_INVALID_VALUE if \( name \) is not one of the supported values.

The method

```cpp
template <cl_int name> typename
detail::param_traits<detail::cl_context_info, name>::param_type
c::Context::getInfo(void)
```

gets specific information about the OpenCL context. Table 4.6 of the *OpenCL Specification* Version 1.2 specifies the information that can be queried. The table above lists `cl_context_info` values that differ in return type between the OpenCL C API and the OpenCL C++ API.

\( name \) is an enumeration constant that identifies the context information being queried. It can be one of the values specified in table 4.6.

**cl::Context::getInfo** returns the appropriate value for a given \( name \) as specified in table 4.6.

The method

```cpp
cl_int cl::Context::getSupportedImageFormats(
    cl_mem_flags flags,
    cl_mem_object_type image_type,
    VECTOR_CLASS<ImageFormat> * formats)
```

can be used to get the list of image formats supported by an OpenCL implementation for the context, when the following information about an image memory object is specified:
- Context
- Image type - 2D, or 3D image.
- Image object allocation information
flags is a bit-field that specifies allocation and usage information about the image memory object being created, as described in table 5.3 of the OpenCL Specification Version 1.2.

image_type describes the image type. It must be either CL_MEM_OBJECT_IMAGE2D or CL_MEM_OBJECT_IMAGE3D.

formats is a pointer to a memory location where the vector of supported image formats is returned. Each entry describes an instance of the class cl::ImageFormat, which is a mapping for cl_image_format structure supported by the OpenCL implementation. If formats is NULL, it is ignored.

cl::Context::getSupportedImageFormats returns CL_SUCCESS on success. Otherwise, it returns one of the following errors:
- CL_INVALID_VALUE if flags or image_type are not valid.
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

3. C++ Runtime layer

3.1 Memory Objects

Class cl::Memory provides a base class for working with OpenCL memory objects. It is used to build buffers and images in the following sections.

The method

```
template <typename T>
cl_int cl::Memory::getInfo(cl_context_info name,
                          T * param)
```

gets specific information about the OpenCL memory object. Table 5.11 of the OpenCL Specification Version 1.2 specifies the information that can be queried. The table below lists cl_memory_info values that differ in return type between the OpenCL C API and the OpenCL C++ API.

<table>
<thead>
<tr>
<th>cl_memory_info</th>
<th>C++ return Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_MEM_CONTEXT</td>
<td>cl::Context</td>
</tr>
</tbody>
</table>

Table 4: Differences in cl::Memory::getInfo return type vs. OpenCL Specification table 5.11

T is a compile time argument that is the return type for the specific information being queried. It corresponds to the values in tables 5.11.

name is an enumeration constant that identifies the context information being queried. It can be one of the values specified in table 5.11.

param is a pointer to a memory location where the appropriate values for a given name as specified in table 5.11 is returned. If param is NULL, it is ignored.
**cl::Memory::getInfo** returns CL_SUCCESS on success. Otherwise, it returns:

- CL_INVALID_VALUE if `name` is not one of the supported values.

The method

```cpp
template <cl_int name> typename
detail::param_traits<detail::cl_context_info, name>::param_type
cl::Memory::getInfo(void)
```

gets specific information about the OpenCL memory object. Table 5.11 of the *OpenCL Specification* Version 1.2 specifies the information that can be queried. The table above lists **cl_memory_info** values that differ in return type between the OpenCL C API and the OpenCL C++ API.

`name` is an enumeration constant that identifies the memory object information being queried. It can be one of the values specified in table 5.11.

**cl::Memory::getInfo** returns the appropriate value for a given `name` as specified in table 5.11.

The method

```cpp
cl_int cl::Memory::setDestructorCallback(
    void (CL_CALLBACK *pfn_notify)(cl_mem memobj, 
        void *user_data),
    void *user_data = NULL)
```

registers a user callback function that is called when the memory object is deleted and its resources freed. The description of **clSetMemObjectDestructorCallback** in section 5.4 of the *OpenCL Specification* gives a detailed overview.

`pfn_notify` is a callback function registered by the application. This callback function may be called asynchronously by the OpenCL implementation. It is the application’s responsibility to ensure that the callback function is thread-safe. The parameters to the callback function are:

- `memobj` is the memory object being deleted.
- `user_data` is a pointer to user supplied data.

`user_data` is passed as the `user_data` argument when `pfn_notify` is called.

**cl::Memory::setDestructorCallback** returns CL_SUCCESS if executed successfully. Otherwise, it returns one of the following errors:

- CL_INVALID_VALUE if `pfn_notify` is NULL.
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 3.2 Buffers
Class `cl::Buffer : public Memory` provides functionality for working with OpenCL buffers.

The constructor

```cpp
cl::Buffer::Buffer(
    const Context& context,
    cl_mem_flags flags,
    ::size_t size,
    void * host_ptr = NULL,
    cl_int * err = NULL)
```

creates an OpenCL buffer object.

`context` is a valid OpenCL context used to create the buffer object.

`flags` is a bit-field that specifies allocation and usage information, such as the memory arena that used to allocate the buffer object and how it is used. Table 5.3 of the `OpenCL Specification` Version 1.2 describes the valid values for `flags`.

`size` is the size in bytes of the buffer memory object to be allocated.

`host_ptr` is a pointer to buffer data that may already be allocated by the application. The size of the buffer that `host_ptr` points to must be at least `size` bytes.

`err` returns an appropriate error code. If `err` is NULL, no error code is returned.

The constructor

```cpp
cl::Buffer::Buffer(
    cl_mem_flags flags,
    ::size_t size,
    void * host_ptr = NULL,
    cl_int * err = NULL)
```

creates an OpenCL buffer object in the default context.

`flags` is a bit-field that specifies allocation and usage information, such as the memory arena that used to allocate the buffer object and how it is used. Table 5.3 of the `OpenCL Specification` Version 1.2 describes the valid values for `flags`.

`size` is the size in bytes of the buffer memory object to be allocated.

`host_ptr` is a pointer to buffer data that may already be allocated by the application. The size of the buffer that `host_ptr` points to must be at least `size` bytes.

`err` returns an appropriate error code. If `err` is NULL, no error code is returned.

The constructor

```cpp
    template <typename IteratorType>
```
```cpp
cl::Buffer::Buffer(
    IteratorType startIterator,
    IteratorType endIterator,
    bool readonly ,
    bool useHostPtr = true,
    cl_int * err = NULL)
```

creates an initialized OpenCL buffer object.

`startIterator` and `endIterator` of the given `IteratorType` provide start and end iterators for the data source.

`readonly` specifies whether the buffer object is readonly (``cl_mem_flags`` value `CL_MEM_READONLY` or `CL_MEM_READWRITE`).

`useHostPtr` specifies whether the buffer uses a host pointer (``cl_mem_flags`` value `CL_MEM_USE_HOST_PTR`).

`cl::Buffer::Buffer` creates a valid non-zero buffer object and sets `err` to `CL_SUCCESS` if it creates the buffer object successfully. Otherwise, it returns one of the following error values returned in `err`:

- `CL_INVALID_CONTEXT` if context is not a valid context.
- `CL_INVALID_VALUE` if values specified in flags are not valid.
- `CL_INVALID_BUFFER_SIZE` if size is 0.
- `CL_INVALID_HOST_PTR` if `host_ptr` is NULL and `CL_MEM_USE_HOST_PTR` or `CL_MEM_COPY_HOST_PTR` are set in flags or if `host_ptr` is not NULL but `CL_MEM_COPY_HOST_PTR` or `CL_MEM_USE_HOST_PTR` are not set in flags.
- `CL_MEM_OBJECT_ALLOCATION_FAILURE` if there is a failure to allocate memory for buffer object.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

The method

```cpp
cl::Buffer cl::Buffer::createSubBuffer(cl_mem_flags flags,
    cl_buffer_create_type buffer_create_type,
    const void * buffer_create_info,
    cl_int * err = NULL)
```

creates a new buffer object from an existing buffer object.

`flags` is a bit-field that specifies allocation and usage information about the image memory object being created, as described in table 5.3.

`buffer_create_type` and `buffer_create_info` describe the type of buffer object to be created. The list of supported values for `buffer_create_type` and corresponding descriptor that

`buffer_create_info` points to information as described in table 5.4 of the OpenCL Specification Version 1.2.


err returns an appropriate error code. If err is NULL, no error code is returned.

`cl::Buffer::createSubBuffer` returns CL_SUCCESS, in err on success. Otherwise, it returns one of the following errors in err:

- CL_INVALID_VALUE if values specified in flags are not valid.
- CL_INVALID_VALUE if value specified in buffer_create_type is not valid.
- CL_INVALID_VALUE if value specified in buffer_create_info (for a given buffer_create_type) is not valid or if buffer_create_info is NULL.

### 3.2.1 Buffer copy

The method

```c
template <typename IteratorType>
cl_int copy(IteratorType startIterator,
            IteratorType endIterator,
            cl::Buffer &buffer)
```

performs a blocking copy to a buffer.

`startIterator` and `endIterator` of the given IteratorType provide start and end iterators for the data source.

`buffer` gives the destination buffer.

The method

```c
template <typename IteratorType>
cl_int copy(cl::Buffer &buffer,
            IteratorType startIterator,
            IteratorType endIterator)
```

performs a blocking copy from a buffer.

`buffer` gives the source buffer.

`startIterator` and `endIterator` of the given IteratorType provide start and end iterators for the data destination.

### 3.2.2 BufferGL objects

Class `cl::BufferGL : public Buffer` provides functionality for OpenGL buffer interoperability.

The constructor

```c
cl::BufferGL::BufferGL(
    const Context& context,
    cl_mem_flags flags,
```
creates an OpenGL-compatible buffer object.

`context` is a valid OpenCL context used to create the buffer object.

`flags` is a bit-field. Table 5.3 of the *OpenCL Specification* Version 1.2 describes the valid values for `flags`.

`bufobj` is an OpenGL buffer handle.

`err` returns an appropriate error code. If `err` is NULL, no error code is returned.

The method

```cpp
cl_int cl::BufferGL::getObjectInfo(cl_gl_object_type *type,
                                   GLuint *gl_object_name)
```

gets specific information about an OpenGL buffer object.

`type` returns the type of the GL buffer object, as defined in *OpenCL Specification* Version 1.1, section 9.8.5.

`gl_object_name` returns the GL object name used to create the OpenGL renderbuffer object. If `gl_object_name` is NULL, it is ignored.

`cl::BufferGL::getObjectInfo` returns CL_SUCCESS on success.

### 3.2.3 BufferRenderGL objects

Class `cl::BufferRenderGL : public Buffer` provides functionality for OpenGL renderbuffer interoperability.

The constructor

```cpp
cl::BufferRenderGL::BufferRenderGL(
    const Context& context,
    cl_mem_flags flags,
    GLuint bufobj,
    cl_int * err = NULL)
```

creates an OpenGL-compatible renderbuffer object.

`context` is a valid OpenCL context used to create the buffer object.

`flags` is a bit-field. Table 5.3 describes the valid values for `flags`.

`bufobj` is an OpenGL renderbuffer handle.

`err` returns an appropriate error code. If `err` is NULL, no error code is returned.
The method

\[
\text{cl\_int } \text{cl\texttt{::BufferRenderGL\texttt{::}}get\texttt{ObjectInfo}(cl\_gl\_object\_type *type,}
\]
\[
\text{GLuint *gl\_object\_name)}
\]

gets specific information about an OpenGL renderbuffer object.

*type* returns the type of the GL renderbuffer object, as defined in *OpenCL Specification* Version 1.1, section 9.8.5.

*gl\_object\_name* returns the GL object name used to create the OpenGL renderbuffer object. If *gl\_object\_name* is NULL, it is ignored.

**cl\texttt{::BufferRenderGL\texttt{::}}get\texttt{ObjectInfo** returns CL\_SUCCESS on success.

## 3.3 Images

Class **cl\texttt{::Image: public Memory** provides a base class for working with OpenCL image objects. It is used to build 1D, 2D, and 3D images in the following sections.

The method

\[
\text{template <typename } T>}
\]
\[
\text{cl\_int } \text{cl\texttt{::Image\texttt{::}}getImageInfo(cl\_image\_info name,}
\]
\[
T * \text{param)}
\]

gets specific information about the OpenCL image object. Table 5.9 of the *OpenCL Specification* Version 1.2 specifies the information that can be queried.

*T* is a compile time argument that is the return for the specific information being queried. It corresponds to the values in table 5.9.

*name* is an enumeration constant that identifies the context information being queried. It can be one of the values specified in table 5.9.

*param* is a pointer to a memory location where the appropriate values for a given *name* as specified in table 5.9 is returned. If *param* is NULL, it is ignored.

**cl\texttt{::Memory\texttt{::}}getImageInfo** returns CL\_SUCCESS on success. Otherwise, it returns:

- CL\_INVALID\_VALUE if *name* is not one of the supported values.

The method

\[
\text{template <cl\_int name> typename}
\]
\[
\text{detail::param\_traits<detail::cl\_image\_info, name>::param\_type}
\]
\[
\text{cl\texttt{::Image\texttt{::}}getImageInfo(}}\text{void)}
\]

gets specific information about the OpenCL image object. Table 5.9 of the *OpenCL Specification* Version 1.2 specifies the information that can be queried.

`name` is an enumeration constant that identifies the memory object information being queried. It can be one of the values specified in table 5.9.

`cl::Image::getImageInfo` returns the appropriate value for a given `name` as specified in table 5.9.

### 3.3.1 Image1D objects

Class `cl::Image1D : public Image` provides functionality for working with OpenCL 1D images.

The constructor

```cpp
cl::Image1D::Image1D(Context& context,
    cl_mem_flags flags,
    ImageFormat format,
    ::size_t width,
    void * host_ptr = NULL,
    cl_int * err = NULL)
```

creates an OpenCL 1D image object.

`context` is a valid OpenCL context on which the image object is to be created.

`flags` is a bit-field that specifies allocation and usage information about the image object being created. It is described in table 5.3 of the *OpenCL Specification* Version 1.2.

`format` is a class that describes format properties of the image to be allocated. `cl::ImageFormat` is a mapping for OpenCL structure `cl_image_format`. Section 5.3.1.1 of the *OpenCL Specification* Version 1.2 gives a detailed description of the image format descriptor.

`width` gives the width of the image in pixels. It must be greater than or equal to 1.

`host_ptr` is a pointer to the image data that may already be allocated by the application. The size of the buffer that `host_ptr` points to must be \(\geq\) `row_pitch` * height. The size of each element in bytes must be a power of 2. The image data specified by `host_ptr` is stored as a linear sequence of adjacent scanlines. Each scanline is stored as a linear sequence of image elements.

`err` returns an appropriate error code. If `err` is NULL, no error code is returned.

`cl::Image1D::Image1D` returns a valid non-zero image object and sets `err` to CL_SUCCESS if it creates the image object successfully. Otherwise, it returns one of the following error values in `err`:

- CL_INVALID_CONTEXT if context is not a valid context.
- CL_INVALID_VALUE if values specified in `flags` are not valid.
- CL_INVALID_IMAGE_FORMAT_DESCRIPTOR if values specified in `format` are not valid.
- CL_INVALID_IMAGE_SIZE if `width` or `height` are 0 or if they exceed values specified in
  - CL_DEVICE_IMAGE2D_MAX_WIDTH
  - CL_DEVICE_IMAGE2D_MAX_HEIGHT
for all devices in context or if values specified by _row_pitch_ do not follow rules described in the argument description above.

- **CL_INVALID_HOST_PTR** if _host_ptr_ is NULL and _CL_MEM_USE_HOST_PTR_ or _CL_MEM_COPY_HOST_PTR_ are set in flags or if _host_ptr_ is not NULL but _CL_MEM_COPY_HOST_PTR_ or _CL_MEM_USE_HOST_PTR_ are not set in flags.
- **CL_IMAGE_FORMAT_NOT_SUPPORTED** if the _image_format_ is not supported.
- **CL_MEM_OBJECT_ALLOCATION_FAILURE** if there is a failure to allocate memory for image object.
- **CL_INVALID_OPERATION** if there are no devices in context that support images (i.e., _CL_DEVICE_IMAGE_SUPPORT_ specified in table 4.3 is CL_FALSE).
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

Class **cl::Image1DArray** : public **Image** provides functionality for working with arrays of OpenCL 1D images.

The constructor

```cpp
cl::Image1DArray::Image1DArray(Context& context,
                   cl_mem_flags flags,
                   ImageFormat format,
                   ::size_t array_size,
                   ::size_t width,
                   ::size_t row_pitch = 0,
                   void * host_ptr = NULL,
                   cl_int * err = NULL)
```

creates an OpenCL 1D image array object.

_**context**_ is a valid OpenCL context on which the object is to be created.

_**flags**_ is a bit-field that specifies allocation and usage information about the image memory object being created, as described in table 5.3.

_**format**_ is a class that describes format properties of the image to be allocated. **cl::ImageFormat** is a mapping for the OpenCL structure _cl_image_format_. Section 5.3.1.1 gives a detailed description of the image format descriptor.

_**array_size**_ is the number of images in the image array.

_**width**_ is the width of each image in pixels. This value must be greater than or equal to 1.

_**row_pitch**_ is the scan-line pitch in bytes. This must be 0 if _host_ptr_ is NULL and can be either 0 or \( \geq \) _width_ * size of element in bytes if _host_ptr_ is not NULL. If _host_ptr_ is not NULL and _row_pitch_ = 0, _row_pitch_ is calculated as _width_ * size of element in bytes. If _row_pitch_ is not 0, it must be a multiple of the image element size in bytes.
host_ptr is a pointer to the image data that may already be allocated by the application. The size of the buffer that host_ptr points to must be $\geq$ row_pitch * height. The size of each element in bytes must be a power of 2. The image data specified by host_ptr is stored as a linear sequence of adjacent scanlines. Each scanline is stored as a linear sequence of image elements.

err returns an appropriate error code. If err is NULL, no error code is returned.

cl::Image1DArray::Image1DArray returns a valid non-zero object and sets err to CL_SUCCESS if it creates the image array object successfully.

Class cl::Image1DBuffer : public Image provides functionality for working with OpenCL 1D image buffers. The constructor

```
cl::Image1DBuffer::Image1DBuffer(Context& context,
   cl_mem_flags flags,
   ImageFormat format,
   ::size_t width,
   Buffer &buffer,
   void *host_ptr = NULL,
   cl_int *err = NULL)
```

creates an OpenCL 1D image buffer object.

context is a valid OpenCL context on which the object is to be created.

flags is a bit-field that specifies allocation and usage information about the image memory object being created, as described in table 5.3.

format is a class that describes format properties of the image to be allocated. cl::ImageFormat is a mapping for the OpenCL structure cl_image_format. Section 5.3.1.1 gives a detailed description of the image format descriptor.

width is the width of the image in pixels. This value must be greater than or equal to 1.

buffer refers to a valid buffer memory object if the image type is CL_MEM_OBJECT_IMAGE_BUFFER, otherwise it must be NULL.

host_ptr is a pointer to the image data that may already be allocated by the application. The size of the buffer that host_ptr points to must be $\geq$ row_pitch * height. The size of each element in bytes must be a power of 2. The image data specified by host_ptr is stored as a linear sequence of adjacent scanlines. Each scanline is stored as a linear sequence of image elements.

err returns an appropriate error code. If err is NULL, no error code is returned.

cl::Image1DArray::Image1DArray returns a valid non-zero object and sets err to CL_SUCCESS if it creates the image array object successfully.
3.3.2 Image2D objects

Class `cl::Image2D : public Image` provides functionality for working with OpenCL 2D images.

The constructor

```
c::Image2D::Image2D(Context& context,
                     cl_mem_flags flags,
                     ImageFormat format,
                     ::size_t width,
                     ::size_t height,
                     ::size_t row_pitch = 0,
                     void * host_ptr = NULL,
                     cl_int * err = NULL)
```

creates an OpenCL 2D image object.

`context` is a valid OpenCL context on which the image object is to be created.

`flags` is a bit-field that specifies allocation and usage information about the image memory object being created, as described in table 5.3 of the OpenCL Specification Version 1.2.

`format` is a class that describes format properties of the image to be allocated. `cl::ImageFormat` is a mapping for the OpenCL structure `cl_image_format`. Section 5.3.1.1 gives for a detailed description of the image format descriptor.

`width`, and `height` are the width and height of the image in pixels. Each must be greater than or equal to 1.

`row_pitch` is the scan-line pitch in bytes. This must be 0 if `host_ptr` is NULL and can be either 0 or `width * size of element in bytes` if `host_ptr` is not NULL. If `host_ptr` is not NULL and `row_pitch = 0`, `row_pitch` is calculated as `width * size of element in bytes`. If `row_pitch` is not 0, it must be a multiple of the image element size in bytes.

`host_ptr` is a pointer to the image data that may already be allocated by the application. The size of the buffer that `host_ptr` points to must be `>= row_pitch * height`. The size of each element in bytes must be a power of 2. The image data specified by `host_ptr` is stored as a linear sequence of adjacent scanlines. Each scanline is stored as a linear sequence of image elements.

`err` returns an appropriate error code. If `err` is NULL, no error code is returned.

`cl::Image2D::Image2D` returns a valid non-zero image object and sets `err` to CL_SUCCESS if it creates the image object successfully. Otherwise, it returns one of the following error values in `err`:

- `CL_INVALID_CONTEXT` if context is not a valid context.
- `CL_INVALID_VALUE` if values specified in flags are not valid.
- `CL_INVALID_IMAGE_FORMAT_DESCRIPTOR` if values specified in `format` are not valid.
- `CL_INVALID_IMAGE_SIZE` if `width` or `height` are 0 or if they exceed values specified in `CL_DEVICE_IMAGE2D_MAX_WIDTH` or `CL_DEVICE_IMAGE2D_MAX_HEIGHT` respectively for all devices in context or if values specified by `row_pitch` do not follow rules described in the argument description above.
• CL_INVALID_HOST_PTR if host_ptr is NULL and CL_MEM_USE_HOST_PTR or CL_MEM_COPY_HOST_PTR are set in flags or if host_ptr is not NULL but CL_MEM_COPY_HOST_PTR or CL_MEM_USE_HOST_PTR are not set in flags.
• CL_IMAGE_FORMAT_NOT_SUPPORTED if the image_format is not supported.
• CL_MEM_OBJECT_ALLOCATION_FAILURE if there is a failure to allocate memory for image object.
• CL_INVALID_OPERATION if there are no devices in context that support images (i.e., CL_DEVICE_IMAGE_SUPPORT specified in table 4.3 is CL_FALSE).
• CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
• CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

Class cl::Image2DArray : public Image provides functionality for working with arrays of OpenCL 2D images.

The constructor

    cl::Image2DArray::Image2DArray(Context& context,
                                       cl_mem_flags flags,
                                       ImageFormat format,
                                       ::size_t array_size,
                                       ::size_t width,
                                       ::size_t height,
                                       ::size_t row_pitch = 0,
                                       ::size_t slice_pitch = 0,
                                       void * host_ptr = NULL,
                                       cl_int * err = NULL)

creates an OpenCL 2D image array object.

context is a valid OpenCL context on which the object is to be created.

flags is a bit-field that specifies allocation and usage information about the image memory object being created, as described in table 5.3.

format is a class that describes format properties of the image to be allocated. cl::ImageFormat is a mapping for the OpenCL structure cl_image_format. Section 5.3.1.1 gives a detailed description of the image format descriptor.

array_size is the number of images in the image array.

width and height are the width and height of each image in pixels. These must be values greater than or equal to 1.

row_pitch is the scan-line pitch in bytes. This must be 0 if host_ptr is NULL and can be either 0 or >= width * size of element in bytes if host_ptr is not NULL. If host_ptr is not NULL and row_pitch = 0, row_pitch is
calculated as width * size of element in bytes. If row_pitch is not 0, it must be a multiple of the image element size in bytes.

slice_pitch gives the size in bytes of each image in the image array. It must be 0 if host_ptr is NULL. If host_ptr is not NULL, slice_pitch can be either 0 or equal to row_pitch.

host_ptr is a pointer to the image data that may already be allocated by the application. The size of the buffer that host_ptr points to must be >= row_pitch * height. The size of each element in bytes must be a power of 2. The image data specified by host_ptr is stored as a linear sequence of adjacent scanlines. Each scanline is stored as a linear sequence of image elements.

err returns an appropriate error code. If err is NULL, no error code is returned.

cl::Image2DArray::Image2DArray returns a valid non-zero object and sets err to CL_SUCCESS if it creates the image array object successfully.

3.3.3 Image3D objects

Class cl::Image3D : public Image provides functionality for working with OpenCL 3D images.

The constructor

    cl::Image3D::Image3D(const Context& context,
                        cl_mem_flags flags,
                        ImageFormat format,
                        ::size_t width,
                        ::size_t height,
                        ::size_t depth,
                        ::size_t row_pitch = 0,
                        ::size_t slice_pitch = 0,
                        void * host_ptr = NULL,
                        cl_int * err = NULL)

creates an OpenCL 3D image object.

context is a valid OpenCL context on which the image object is to be created.

flags is a bit-field that specifies allocation and usage information about the image memory object being created, as described in table 5.3.

format is a class that describes format properties of the image to be allocated. cl::ImageFormat is a mapping for the OpenCL structure cl_image_format. Section 5.3.1.1 gives a detailed description of the image format descriptor.

width, and height are the width and height of the image in pixels. Each must be greater than or equal to 1.

depth is the depth of the image in pixels. This must be a value > 1.
row_pitch is the scan-line pitch in bytes. This must be 0 if host_ptr is NULL and can be either 0 or >= width * size of element in bytes if host_ptr is not NULL. If host_ptr is not NULL and row_pitch = 0, row_pitch is calculated as width * size of element in bytes. If row_pitch is not 0, it must be a multiple of the image element size in bytes.

slice_pitch is the size in bytes of each 2D slice in the 3D image. This must be 0 if host_ptr is NULL and can be either 0 or >= row_pitch * height if host_ptr is not NULL. If host_ptr is not NULL and slice_pitch = 0, slice_pitch is calculated as row_pitch * height. If slice_pitch is not 0, it must be a multiple of the row_pitch.

host_ptr is a pointer to the image data that may already be allocated by the application. The size of the buffer that host_ptr points to must be >= slice_pitch * depth. The size of each element in bytes must be a power of 2. The image data specified by host_ptr is stored as a linear sequence of adjacent 2D slices. Each 2D slice is a linear sequence of adjacent scanlines. Each scanline is a linear sequence of image elements.

err returns an appropriate error code. If err is NULL, no error code is returned.

cl::Image3D::Image3D returns a valid non-zero image object and sets err to CL_SUCCESS if it creates the image object successfully. Otherwise, it returns one of the following error values in err:

- CL_INVALID_CONTEXT if context is not a valid context.
- CL_INVALID_VALUE if values specified in flags are not valid.
- CL_INVALID_IMAGE_FORMAT_DESCRIPTOR if values specified in format are not valid.
- CL_INVALID_IMAGE_SIZE if width, height are 0 or if depth <= 1 or if they exceed values specified in CL_DEVICE_IMAGE3D_MAX_WIDTH, CL_DEVICE_IMAGE3D_MAX_HEIGHT or CL_DEVICE_IMAGE3D_MAX_DEPTH respectively for all devices in context or if values specified by row_pitch and slice_pitch do not follow rules described in the argument description above.
- CL_INVALID_HOST_PTR if host_ptr is NULL and CL_MEM_USE_HOST_PTR or CL_MEM_COPY_HOST_PTR are set in flags or if host_ptr is not NULL but CL_MEM_COPY_HOST_PTR or CL_MEM_USE_HOST_PTR are not set in flags.
- CL_IMAGE_FORMAT_NOT_SUPPORTED if the image_format is not supported.
- CL_MEM_OBJECT_ALLOCATION_FAILURE if there is a failure to allocate memory for image object.
- CL_INVALID_OPERATION if there are no devices in context that support images (i.e. CL_DEVICE_IMAGE_SUPPORT specified in table 4.3 is CL_FALSE).
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

3.3.4 ImageGL objects

Class cl::ImageGL : public Image provides functionality for OpenGL image interoperability. This class abstracts all OpenGL images (1D, 2D, and 3D).

The constructor

    cl::ImageGL::ImageGL(Context& context,
                          cl_mem_flags flags,
                          GLenum target,
                          GLint mipmap,
GLuint texobj,
cl_int * err = NULL)

does not create an OpenGL image object.

context is a valid OpenCL context on which the image object is to be created.

flags is a bit-field that specifies allocation and usage information about the image object being created and is
described in table 5.3 of the OpenCL Specification Version 1.2.

target is an OpenGL texture type, as defined in section 9.8.3 of the OpenCL Specification Version 1.1.

miplevel is the mipmap level to be used.

texobj is the name of an OpenGL texture object.

err returns an appropriate error code. If err is NULL, no error code is returned.

cl::ImageGL::ImageGL returns a valid non-zero image object and sets err to CL_SUCCESS if it creates the
image object successfully.

### 3.4 Samplers

Class cl::Sampler provides functionality for working with OpenCL samplers.

The constructor

```
class Sampler::Sampler(const Context& context,
    cl_bool normalized_coords,
    cl_addressing_mode addressing_mode,
    cl_filter_mode filter_mode,
    cl_int * err = NULL)
```

does not create an OpenCL sampler object. Refer to section 6.11.13.1 for a detailed description of how samplers work.

context must be a valid OpenCL context.

normalized_coords determines if the image coordinates specified are normalized (if normalized_coords is
CL_TRUE) or not (if normalized_coords is CL_FALSE).

addressing_mode specifies how out-of-range image coordinates are handled when reading from an image. It
can be CL_ADDRESS_MIRRORED_REPEAT, CL_ADDRESS_REPEAT,
CL_ADDRESS_CLAMP_TO_EDGE, CL_ADDRESS_CLAMP, or CL_ADDRESS_NONE.

filtering_mode specifies the type of filter that must be applied when reading an image. It can be
CL_FILTER_NEAREST, or CL_FILTER_LINEAR.

err returns an appropriate error code. If err is NULL, no error code is returned.
cl::Sampler::Sampler constructs a valid non-zero sampler object and sets err to CL_SUCCESS if it creates the sampler object successfully. Otherwise, it returns one of the following error values in err:

- CL_INVALID_CONTEXT if context is not a valid context.
- CL_INVALID_VALUE if an argument value for addressing_mode, filter_mode, or normalized_coords is not valid.
- CL_INVALID_OPERATION if images are not supported by any device associated with context (i.e., CL_DEVICE_IMAGE_SUPPORT specified in table 4.3 is CL_FALSE).
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The method

```cpp
template <typename T>
cl_int cl::Sampler::getInfo(cl_sampler_info name, 
                          T * param)
```

gets specific information about the OpenCL Sampler. Table 5.12 of the OpenCL Specification Version 1.2 specifies the information that can be queried. The table below lists cl_sampler_info values that differ in return type between the OpenCL C API and the OpenCL C++ API.

<table>
<thead>
<tr>
<th>cl_sampler_info</th>
<th>C++ return Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_SAMPLER_CONTEXT</td>
<td>cl::Context</td>
</tr>
</tbody>
</table>

Table 5: Differences in cl::Sampler::getInfo return type vs. OpenCL Specification table 5.12

T is a compile time argument that is the return for the specific information being queried. It corresponds to the values in tables 5.12.

name is an enumeration constant that identifies the sampler information being queried. It can be one of the values specified in table 5.12.

param is a pointer to a memory location where the appropriate values for a given name as specified in table 5.12 is returned.

If param is NULL, it is ignored.

cl::Sampler::getInfo returns CL_SUCCESS on success. Otherwise, it returns:

- CL_INVALID_VALUE if name is not one of the supported values.

The method

```cpp
template <cl_int name> typename
detail::param_traits<detail::cl_sampler_info, name>::param_type
cl::Sampler::getInfo(void)
```

gets specific information about the OpenCL sampler. Table 5.12 of the OpenCL Specification Version 1.2 specifies the information that can be queried. The table above lists cl_sampler_info values that differ in return type between the OpenCL C API and the OpenCL C++ API.
name is an enumeration constant that identifies the sampler information being queried. It can be one of the values specified in table 5.12.

`cl::Sampler::getInfo` returns the appropriate value for a given `name` as specified in table 5.12.

## 3.5 Programs

Class `cl::Program` provides functionality for working with OpenCL programs.

Class `cl::Program` provides two public typedefs for working with source files and binaries, respectively:

```cpp
typedef VECTOR_CLASS<std::pair<const void*, ::size_t> > Binaries
```

and

```cpp
typedef VECTOR_CLASS<std::pair<const char*, ::size_t> > Sources
```

The constructor

```cpp
cl::Program::Program(const STRING_CLASS& source,
                      cl_int * err = NULL)
```

creates and builds an OpenCL program object.

`soure` is the program source code.

`err` returns an appropriate error code. If `err` is `NULL`, no error code is returned.

The constructor

```cpp
cl::Program::Program(const STRING_CLASS& source,
                      bool build,
                      cl_int * err = NULL)
```

creates an OpenCL program object.

`soure` is the program source code.

`bool` is a flag that indicates whether to build the program.

`err` returns an appropriate error code. If `err` is `NULL`, no error code is returned.

The constructor

```cpp
cl::Program::Program(const Context& context,
                      const STRING_CLASS& source,
```
bool build,
cl_int * err = NULL)

creates an OpenCL program object for an OpenCL context.

context must be a valid OpenCL context.

source is the program source code.

bool is a flag that indicates whether to build the program.

er returns an appropriate error code. If err is NULL, no error code is returned.

The constructor

```
class::Program::Program(const Context& context,
    const Sources& sources,
    cl_int * err = NULL)
```

creates an OpenCL program object for a context and loads the source code specified by the text strings in each element of the vector sources into the program object.

context must be a valid OpenCL context.

sources is a vector of source/size tuples that make up the source code.

er returns an appropriate error code. If err is NULL, no error code is returned.

```
class::Program::Program(const Context& context,
    const VECTOR_CLASS<Device>& devices,
    const Binaries& binaries,
    VECTOR_CLASS<cl_int> * binaryStatus = NULL,
    cl_int * err = NULL)
```

creates an OpenCL program object for a context and loads the binary bits specified by the binary in each element of the vector binaries into the program object.

context must be a valid OpenCL context.
devices is a list of devices. devices must be of non-zero length and each device specified by devices must be associated with context. The binaries are loaded for devices specified in this list. The devices associated with the program object will be the given devices.

binaries is a vector of program binaries to be loaded for devices specified by devices. For each devices[i], the program binary for that device is binaries[i].

binary_status returns whether the program binary for each device specified in devices was loaded successfully. It is an array of num_devices entries. binary_status[i] returns CL_SUCCESS if the binary for devices[i] is successfully loaded or CL_INVALID_BINARY if program binaries[i] is not a valid binary for devices[i]. If binary_status is NULL, it is ignored.

er returns an appropriate error code. If err is NULL, no error code is returned.

cl::Program::Program returns a valid program object and sets err to CL_SUCCESS if it creates the program object successfully. Otherwise, it returns one of the following error values returned in err:

- CL_INVALID_CONTEXT if context is not a valid context.
- CL_INVALID_VALUE if devices is of length zero.
- CL_INVALID_DEVICE if OpenCL devices listed in devices are not in the list of devices associated with context.
- CL_INVALID_VALUE if binaries is length 0 or if any entry in binaries is not valid.
- CL_INVALID_BINARY if an invalid program binary was encountered for any device. binary_status returns specific status for each device.
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The constructor

    cl::Program::Program(const Context& context,
                          const VECTOR_CLASS<Device>& devices,
                          STRING_CLASS& kernelNames,
                          cl_int* err = NULL)

creates an OpenCL program object with a set of built-in kernel names for a context.

context must be a valid OpenCL context.

devices is a vector list of devices that are in context. devices must be of non-zero length and each device specified by devices must be associated with context. The binaries are loaded for devices specified in this list. The devices associated with the program object will be the given devices.

kernelNames is a semi-colon separated list of built-in kernel names.

cl::Program::Program returns a valid program object and sets err to CL_SUCCESS if it creates the program object successfully.
The method

```cpp
cl_int cl::Program::build(const VECTOR_CLASS<Device> devices,
const char * options = NULL,
(CL_CALLBACK * pfn_notify)
(cl_program,
 void * user_data) = NULL,
 void * data = NULL)
```

builds (compiles and links) a program executable from the program source or binary for all the devices or specific devices in the OpenCL context associated with program.

`devices` is a list of devices associated with program. If `devices` is of length zero, the program executable is built for all devices associated with program for which a source or binary has been loaded. If `devices` is of non-zero length, the program executable is built for devices specified in the list for which a source or binary has been loaded.

`options` is a pointer to a string that describes the build options to be used for building the program executable. Section 5.6.4 of the *OpenCL Specification* Version 1.2 describes the supported options.

`pfn_notify` is a function pointer to a notification routine. The notification routine is a callback function that an application can register and which is called when the program executable has been built (successfully or unsuccessfully). If `pfn_notify` is not NULL, `cl::Program::build` does not need to wait for the build to complete and can return immediately. If `pfn_notify` is NULL, `cl::Program::build` does not return until the build has completed. This callback function may be called asynchronously by the OpenCL implementation. It is the application’s responsibility to ensure that the callback function is thread-safe.

`data` is passed as an argument when `pfn_notify` is called. `data` can be NULL.

`cl::Program::build` returns CL_SUCCESS on success. Otherwise, it returns one of the following errors:

- CL_INVALID_VALUE if `pfn_notify` is NULL but `data` is not NULL.
- CL_INVALID_DEVICE if OpenCL devices listed in `devices` are not in the list of devices associated with program.
- CL_INVALID_BINARY if program is created with `cl::Program::Program` and devices listed in `devices` do not have a valid program binary loaded.
- CL_INVALID_BUILD_OPTIONS if the build options specified by options are invalid.
- CL_INVALID_OPERATION if the build of a program executable for any of the devices listed in `devices` by a previous call to `cl::Program::build` for program has not completed.
- CL_COMPILER_NOT_AVAILABLE if program is created from source and a compiler is not available, i.e., CL_DEVICE_COMPILER_AVAILABLE specified in table 4.3 is set to CL_FALSE.
- CL_BUILD_PROGRAM_FAILURE if there is a failure to build the program executable. This error is returned if `cl::Program::build` does not return until the build has completed.
- CL_INVALID_OPERATION if there are kernel objects attached to program.
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The method
builds (compiles and links) a program executable from the program source or binary in the OpenCL context associated with program.

'options' is a pointer to a string that describes the build options to be used for building the program executable. The list of supported options is described in section 5.6.4 of the 'OpenCL Specification' Version 1.2.

'pfn_notify' is a function pointer to a notification routine. The notification routine is a callback function that an application can register and which is called when the program executable has been built (successfully or unsuccessfully). If 'pfn_notify' is not NULL, 'cl::Program::build' does not need to wait for the build to complete and can return immediately. If 'pfn_notify' is NULL, 'cl::Program::build' does not return until the build has completed. This callback function may be called asynchronously by the OpenCL implementation. The application must ensure that the callback function is thread-safe.

'data' is passed as an argument when 'pfn_notify' is called. 'data' can be NULL.

'cl::Program::build' returns CL_SUCCESS on success.

The method

\[
\text{cl_int cl::Program::build(const char * options = NULL,}
\]
\[
\text{(CL_CALLBACK * pfn_notify)}
\]
\[
\text{(cl_program,}
\]
\[
\text{void * user_data) = NULL,}
\]
\[
\text{void * data = NULL)}
\]

compiles (but does not link) a program executable from the program source or binary in the OpenCL context associated with program.

'options' is a pointer to a string that describes the compilation options to be used for building the program executable. Section 5.6.4 of the 'OpenCL Specification' Version 1.2 describes the list of supported options.

'pfn_notify' is a function pointer to a notification routine. The notification routine is a callback function that an application can register and which is called when the program executable has been built (successfully or unsuccessfully). If 'pfn_notify' is not NULL, 'cl::Program::build' does not need to wait for the build to complete and can return immediately. If 'pfn_notify' is NULL, 'cl::Program::build' does not return until the build has completed. This callback function may be called asynchronously by the OpenCL implementation. It is the application’s responsibility to ensure that the callback function is thread-safe.

'data' is passed as an argument when 'pfn_notify' is called. 'data' can be NULL.

'cl::Program::compile' returns CL_SUCCESS on success.

The method

\[
\text{cl_int cl::Program::compile(const char * options = NULL,}
\]
\[
\text{(CL_CALLBACK * pfn_notify)}
\]
\[
\text{(cl_program,}
\]
\[
\text{void * user_data) = NULL,}
\]
\[
\text{void * data = NULL)}
\]
cl_int cl::Program::linkProgram(Program input1,
    Program input2,
    const char * options = NULL,
    (CL_CALLBACK * pfn_notify)
    (cl_program,
        void * user_data) = NULL,
    void * data = NULL,
    cl_int *err = NULL)

links programs input1 and input2.

input1 and input2 are program objects.

options is a pointer to a string that describes the compilation options to be used for linking the program executable. The list of supported options is described in section 5.6.4 of the OpenCL Specification 1.2.

pfn_notify is a function pointer to a notification routine. The notification routine is a callback function registered by the application which is called when the program executable has been built (successfully or unsuccessfully). If pfn_notify is not NULL, cl::Program::build does not need to wait for the build to complete and can return immediately. If pfn_notify is NULL, cl::Program::build does not return until the build has completed. This callback function may be called asynchronously by the OpenCL implementation. The application must ensure that the callback function is thread-safe.

data is passed as an argument when pfn_notify is called. data can be NULL.

cl::Program::linkProgram returns CL_SUCCESS if executed successfully.

The method

cl_int cl::Program::linkProgram(VECTOR_CLASS<Program> InputPrograms,
    const char * options = NULL,
    (CL_CALLBACK * pfn_notify)
    (cl_program,
        void * user_data) = NULL,
    void * data = NULL,
    cl_int *err = NULL)

links a set of programs.

InputPrograms is a set of program objects.

options is a pointer to a string that describes the compilation options to be used for linking the program executable. The list of supported options is described in section 5.6.4 of the OpenCL Specification Version 1.2.

pfn_notify is a function pointer to a notification routine. The notification routine is a callback function registered by the application which is called when the program executable has been built (successfully or unsuccessfully). If pfn_notify is not NULL, cl::Program::build does not need to wait for the build to complete and returns immediately. If pfn_notify is NULL, cl::Program::build does not return until the build has completed. This
callback function may be called asynchronously by the OpenCL implementation. The application must ensure that the callback function is thread-safe.

*data* is passed as an argument when *PFN_notify* is called. *data* can be NULL.

**cl::Program::linkProgram** returns CL_SUCCESS if executed successfully.

The method

```cpp
template <typename T>
cl_int cl::Program::getInfo(cl_program_info name, 
    T * param)
```

gets specific information about the OpenCL Program. Table 5.13 of the *OpenCL Specification* Version 1.2 specifies the information that can be queried. The table below lists **cl_program_info** values that differ in return type between the OpenCL C API and the OpenCL C++ API.

<table>
<thead>
<tr>
<th>cl_program_info</th>
<th>C++ return Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_PROGRAM_BINARIES</td>
<td>VECTOR_CLASS&lt;char *&gt;</td>
</tr>
<tr>
<td>CL_PROGRAM_BINARY_SIZES</td>
<td>VECTOR_CLASS&lt;::size_t&gt;</td>
</tr>
<tr>
<td>CL_PROGRAM_CONTEXT</td>
<td>cl::Context</td>
</tr>
<tr>
<td>CL_PROGRAM_DEVICES</td>
<td>VECTOR_CLASS&lt;cl_device_id&gt;</td>
</tr>
<tr>
<td>CL_PROGRAM_KERNEL_NAMES</td>
<td>STRING_CLASS</td>
</tr>
<tr>
<td>CL_PROGRAM_SOURCE</td>
<td>STRING_CLASS</td>
</tr>
</tbody>
</table>

*Table 6: Differences in cl::Program::getInfo return type vs. OpenCL Specification table 5.13*

*name* is a compile time argument that is the return for the specific information being queried. It corresponds to the values in table 5.13.

*name* is an enumeration constant that identifies the program information being queried. It can be one of the values specified in table 5.13.

*param* is a pointer to a memory location where the appropriate values for a given *name* as specified in table 5.13 is returned. If *param* is NULL, it is ignored.

**cl::Program::getInfo** returns CL_SUCCESS on success. Otherwise, it returns:

- CL_INVALID_VALUE if *name* is not one of the supported values.

The method

```cpp
template <cl_int name> typename
detail::param_traits<detail::cl_program_info, name>::param_type
cl::Program::getInfo(void)
```

gets specific information about the OpenCL program. Table 5.13 of the *OpenCL Specification* Version 1.2 specifies the information that can be queried. The table above lists **cl_program_info** values that differ in return type between the OpenCL C API and the OpenCL C++ API.

*name* is an enumeration constant that identifies the program information being queried. It can be one of the values specified in table 5.13.
**cl::Program::getInfo** returns the appropriate value for a given *name* as specified in table 5.13.

The method

```cpp
template <typename T>
cl_int cl::Program::getBuildInfo(cl_program_build_info name, T * param)
```

returns build information for each device in the program object. Table 5.14 of the *OpenCL Specification* Version 1.2 specifies the information that can be queried. The table below lists **cl_program_build_info** values that differ in return type between the OpenCL C API and the OpenCL C++ API.

<table>
<thead>
<tr>
<th>cl_program_build_info</th>
<th>C++ return Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_PROGRAM_BUILD_LOG</td>
<td>STRING_CLASS</td>
</tr>
<tr>
<td>CL_PROGRAM_BUILD_OPTIONS</td>
<td>STRING_CLASS</td>
</tr>
</tbody>
</table>

*Table 7: Differences in cl::Program::getBuildInfo return type vs. *OpenCL Specification* table 5.14*

*T* is a compile time argument that is the return type for the specific information being queried. It corresponds to the values in tables 5.14.

*name* is an enumeration constant that identifies the program build information being queried. It can be one of the values specified in table 5.14.

*param* is a pointer to a memory location where the appropriate values for a given *name* as specified in table 5.14 is returned. If *param* is NULL, it is ignored.

**cl::Program::getBuildInfo** returns CL_SUCCESS on success. Otherwise, it returns:

- CL_INVALID_VALUE if *name* is not one of the supported values.

The method

```cpp
template <cl_int name> typename
detail::param_traits<detail::cl_program_info, name>::param_type
cl::Program::getBuildInfo(void)
```

returns build information for each device in the program object. Table 5.14 of the *OpenCL Specification* Version 1.2 specifies the information that can be queried. The table above lists **cl_program_build_info** values that differ in return type between the OpenCL C API and the OpenCL C++ API.

*name* is an enumeration constant that identifies the program information being queried. It can be one of the values specified in table 5.14.

**cl::Program::getBuildInfo** returns the appropriate value for a given *name* as specified in table 5.14.

The method

```cpp
cl_int cl::Program::createKernels(const VECTOR_CLASS<Kernel> * kernels)
```
creates kernel objects (i.e., objects of type `cl::Kernel`, see section 3.6 below) for all kernels in the program.

`kernels` is a pointer to a vector where the kernel objects for `kernels` in the program is returned.

`c::Program::createKernels` returns CL_SUCCESS if the kernel objects were successfully allocated. Otherwise, it returns one of the following errors:

- CL_INVALID_PROGRAM_EXECUTABLE if there is no successfully built executable for any device in program.
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 3.6 Kernels

Class `cl::Kernel` provides functionality for working with OpenCL kernels.

The constructor

```cpp
cl::Kernel::Kernel(const Program& program,
                    const char * name,
                    cl_int * err = NULL)
```

creates a kernel object.

`program` is a program object with a successfully built executable.

`name` is a function name in the program declared with the __kernel qualifier.

`err` returns an appropriate error code. If `err` is NULL, no error code is returned.

`cl::Kernel::Kernel` returns a valid kernel object and sets `err` to CL_SUCCESS if it creates the kernel object successfully. Otherwise, it returns one of the following error values returned in `err`:

- CL_INVALID_PROGRAM if program is not a valid program object.
- CL_INVALID_PROGRAM_EXECUTABLE if there is no successfully built executable for program.
- CL_INVALID_KERNEL_NAME if `name` is not found in program.
- CL_INVALID_KERNEL_DEFINITION if the function definition for __kernel function given by `name` such as the number of arguments, the argument types are not the same for all devices for which the program executable has been built.
- CL_INVALID_VALUE if `name` is NULL.
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The method

```cpp
template <typename T>
cl_int cl::Kernel::getInfo(cl_kernel_info name,
```


gets specific information about the OpenCL kernel. Table 5.15 of the OpenCL Specification Version 1.2 specifies the information that can be queried. The table below lists cl_kernel_info values that differ in return type between the OpenCL C API and the OpenCL C++ API.

<table>
<thead>
<tr>
<th>cl_kernel_info</th>
<th>C++ return Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_KERNEL_ATTRIBUTES</td>
<td>STRING_CLASS</td>
</tr>
<tr>
<td>CL_KERNEL_CONTEXT</td>
<td>cl::Context</td>
</tr>
<tr>
<td>CL_KERNEL_FUNCTION_NAME</td>
<td>STRING_CLASS</td>
</tr>
<tr>
<td>CL_KERNEL_PROGRAM</td>
<td>cl::Program</td>
</tr>
</tbody>
</table>

Table 8: Differences in cl::Kernel::getInfo return type vs. OpenCL Specification table 5.15

$T$ is a compile time argument that is the return type for the specific information being queried. It corresponds to the values in table 5.15.

$name$ is an enumeration constant that identifies the kernel information being queried. It can be one of the values specified in table 5.15.

$param$ is a pointer to a memory location where the appropriate values for a given $name$ as specified in table 5.15 is returned. If $param$ is NULL, it is ignored.

cl::Kernel::getInfo returns CL_SUCCESS on success. Otherwise, it returns:
- CL_INVALID_VALUE if $name$ is not one of the supported values.

The method

```cpp
template <cl_int name> typename
detail::param_traits<detail::cl_kernel_info, name>::param_type
cl::Kernel::getInfo(void)
```

gets specific information about the OpenCL kernel. Table 5.15 of the OpenCL Specification Version 1.2 specifies the information that can be queried. The table above lists cl_kernel_info values that differ in return type between the OpenCL C API and the OpenCL C++ API.

$name$ is an enumeration constant that identifies the kernel information being queried. It can be one of the values specified in table 5.15.

cl::Kernel::getInfo returns the appropriate value for a given $name$ as specified in table 5.15.

The method

```cpp
template <typename T>
cl_int cl::Kernel::getArgInfo(cl_uint argIndex,
                               cl_kernel_arg_info name,
                               T * param)
```
gets specific information about an OpenCL kernel argument. Table 5.17 of the *OpenCL Specification* Version 1.2 specifies the information that can be queried. The table below lists `cl_kernel_arg_info` values that differ in return type between the OpenCL C API and the OpenCL C++ API.

<table>
<thead>
<tr>
<th>cl_kernel_arg_info</th>
<th>C++ return Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_KERNEL_ARG_NAME</td>
<td>STRING_CLASS</td>
</tr>
<tr>
<td>CL_KERNEL_ARG_TYPE_NAME</td>
<td>STRING_CLASS</td>
</tr>
</tbody>
</table>

Table 9: Differences in `cl::Kernel::getArgInfo` return type vs. *OpenCL Specification* table 5.17

*T* is a compile time argument that is the return type for the specific information being queried. It corresponds to the values in table 5.15.

*argIndex* is the index of the kernel argument being queried.

*name* is an enumeration constant that identifies the kernel argument information being queried. It can be one of the values specified in table 5.17.

*param* is a pointer to a memory location where the appropriate values for a given *name* as specified in table 5.17 is returned. If *param* is NULL, it is ignored.

`cl::Kernel::getArgInfo` returns CL_SUCCESS on success.

The method

```cpp
template <cl_int name> typename
detail::param_traits<detail::cl_kernel_arg_info, name>::param_type
cl::Kernel::getArgInfo(xl_uint argIndex, cl_int* err)
```

gets specific information about an OpenCL kernel argument. Table 5.15 of the *OpenCL Specification* Version 1.2 specifies the information that can be queried. The table above lists `cl_kernel_arg_info` values that differ in return type between the OpenCL C API and the OpenCL C++ API.

*name* is an enumeration constant that identifies the kernel information being queried. It can be one of the values specified in table 5.17.

*argIndex* is the index of the kernel argument being queried.

`cl::Kernel::getArgInfo` returns the appropriate value for a given *name* as specified in table 5.17.

The method

```cpp
template <typename T>
c_int cl::Kernel::getWorkGroupInfo(cl_kernel_work_group_info name,
T* param)
```

gets specific information about the OpenCL kernel object that may be specific to a device. Table 5.16 of the *OpenCL Specification* Version 1.2 specifies the information that can be queried. The table below lists `cl_kernel_work_group_info` values that differ in return type between the OpenCL C API and the OpenCL C++ API.
<table>
<thead>
<tr>
<th>cl_kernel_work_group_info</th>
<th>C++ return Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_KERNEL_COMPILE_WORK_GROUP_SIZE</td>
<td>cl::size_t&lt;3&gt;^2</td>
</tr>
</tbody>
</table>

Table 10: Differences in cl::Kernel::getWorkGroupInfo return type vs. OpenCL Specification table 5.16

*T* is a compile time argument that is the return type for the specific information being queried. It corresponds to the values in tables 5.16.

*name* is an enumeration constant that identifies the kernel information being queried. It can be one of the values specified in table 5.16.

*param* is a pointer to a memory location where the appropriate values for a given *name* as specified in table 5.16 is returned. If *param* is NULL, it is ignored.

```cpp
template <cl_int name> typename
detail::param_traits<detail::cl_kernel_work_group_info, name>::param_type
cl::Kernel::getWorkGroupInfo(void)
```

gets specific information about the OpenCL kernel object that may be specific to a device. Table 5.16 of the OpenCL Specification Version 1.2 specifies the information that can be queried. The table above lists *cl_kernel_work_group_info* values that differ in return type between the OpenCL C API and the OpenCL C++ API.

*name* is an enumeration constant that identifies the kernel information being queried. It can be one of the values specified in table 5.16.

```cpp
template <typename T>
cl_int cl::Kernel::setArg(cl_uint index,
T value)
```

sets the argument value for a specific argument of a kernel.

*T* is a compile time argument that determines the type of a kernel argument being set. It can be one of the following:

- A *cl::Memory* object. e.g. a *cl::Buffer* or *cl::Image3D* would be possible values.
- A *cl::Sampler* object.

^2 cl::size_t<3> is a internal type that can be treated as a 3D array whose components correspond to x,y,z values of the work-group size.
- A value of type `cl::LocalSpaceArg`, which corresponds to an argument of `__local` in the kernel object.
- A constant value that is passed by value to the kernel.

`index` is the argument index. Arguments to the kernel are referred by indices that go from 0 for the leftmost argument to `n-1`, where `n` is the total number of arguments declared by a kernel.

`value` is the data that should be used as the argument value for argument specified by `index`.

`cl::Kernel::setArg` returns CL_SUCCESS if the function was executed successfully. Otherwise, it returns one of the following errors:

- CL_INVALID_ARG_INDEX if `index` is not a valid argument index.
- CL_INVALID_MEM_OBJECT for an argument declared to be a memory object when the specified `value` is not a valid memory object.
- CL_INVALID_SAMPLER for an argument declared to be of type `cl::Sampler` when the specified `value` is not a valid sampler object.

### 3.6.1 Kernel functors

Kernel functors provide additional functionality to simplify kernel invocations. The template

```cpp
template <typename T0, typename T1 = detail::NullType, typename T2 = detail::NullType, typename T3 = detail::NullType, typename T4 = detail::NullType, typename T5 = detail::NullType, typename T6 = detail::NullType, typename T7 = detail::NullType, typename T8 = detail::NullType, typename T9 = detail::NullType, typename T10 = detail::NullType, typename T11 = detail::NullType, typename T12 = detail::NullType, typename T13 = detail::NullType, typename T14 = detail::NullType, typename T15 = detail::NullType, typename T16 = detail::NullType, typename T17 = detail::NullType, typename T18 = detail::NullType, typename T19 = detail::NullType, typename T20 = detail::NullType, typename T21 = detail::NullType, typename T22 = detail::NullType, typename T23 = detail::NullType, typename T24 = detail::NullType, typename T25 = detail::NullType, typename T26 = detail::NullType, typename T27 = detail::NullType, typename T28 = detail::NullType, typename T29 = detail::NullType, typename T30 = detail::NullType, typename T31 = detail::NullType>
struct make_kernel::detail::functionImplementation<T0, T1, T2, T3, T4, T5, T6, T7, T8, T9, T10, T11, T12, T13, T14, T15, T16, T17, T18, T19, T20, T21, T22, T23, T24, T25, T26, T27, T28, T29, T30, T31> {
    cl::make_kernel::make_kernel(
        const Program &program,
        const STRING_CLASS name,
        cl_int *err = NULL)
}
```

makes a kernel functor for a kernel with 1 to 32 arguments.

`T0` to `T31` are the kernel argument types.

`program` is the OpenCL program that defines the kernel.

---

3 The function `cl::LocalSpaceArg cl::__local(::size_t)` can be used to construct arguments specifying the size of a `__local` kernel argument. For example, `cl::__local(100)` would allocate `sizeof(cl_char) * 100` of local memory.
name is the name of the kernel functor.

err returns an appropriate error code. If err is NULL, no error is returned.

The template

template <typename T0, typename T1 = detail::NullType, typename T2 = detail::NullType,
        typename T3 = detail::NullType, typename T4 = detail::NullType, typename T5 = detail::NullType,
        typename T6 = detail::NullType, typename T7 = detail::NullType, typename T8 = detail::NullType,
        typename T9 = detail::NullType, typename T10 = detail::NullType, typename T11 = detail::NullType,
        typename T12 = detail::NullType, typename T13 = detail::NullType, typename T14 = detail::NullType,
        typename T15 = detail::NullType, typename T16 = detail::NullType, typename T17 = detail::NullType,
        typename T18 = detail::NullType, typename T19 = detail::NullType, typename T20 = detail::NullType,
        typename T21 = detail::NullType, typename T22 = detail::NullType, typename T23 = detail::NullType,
        typename T24 = detail::NullType, typename T25 = detail::NullType, typename T26 = detail::NullType,
        typename T27 = detail::NullType, typename T28 = detail::NullType, typename T29 = detail::NullType,
        typename T30 = detail::NullType, typename T31 = detail::NullType>

struct make_kernel :: detail::functionImplementation<T0, T1, T2, T3, T4, T5, T6, T7, T8, T9, T10,
        T11, T12, T13, T14, T15, T16, T17, T18, T19, T20, T21, T22, T23, T24, T25, T26, T27, T28, T29, T30, T31>

cl::make_kernel :: make_kernel(
    const Kernel kernel,
    cl_int *err = NULL)

makes a kernel functor for the given kernel with 1 to 32 arguments.

T0 to T31 are the kernel argument types.

err returns an appropriate error code. If err is NULL, no error is returned.

The overloaded operator () for a kernel functor invocation takes one of the following forms:

    Event operator() { EnqueueArgs& args,
                        T0 t0, T1 t1 = NullType, …, T31 t31 = NullType}

    Event operator() { EnqueueArgs& args,
                      const Event& waitEvent,
                      T0 t0, T1 t1 = NullType, …, T31 t31 = NullType }

    Event operator() { EnqueueArgs &args,
                      const VECTOR_CLASS<Event>& waitEvents,
                      T0 t0, T1 t1 = NullType, …, T31 t31 = NullType }

The first enqueues the kernel’s arguments, invokes the kernel, and returns an event object representing the
kernel execution. The second and third forms are similar, but the second waits for the completion of the given
waitEvent before invoking the kernel, while the third waits for completion of all waitEvents before invoking the
kernel.

For example, suppose myKernelProgram is a Program with a string defining the source for kernel myKernel,
and suppose myKernel takes three Buffer arguments (two input buffers and an output buffer). Then:

typedef cl::make_kernel <cl::Buffer&, cl::Buffer&, cl::Buffer&> KernelType;
std::function<KernelType::type_> myKernel = KernelType(myKernelProgram, “myKernel”);
constructs kernel functor myKernel. Similarly, using auto (for C++11 users):

```c++
auto myKernel = cl::make_kernel<cl::Buffer&, cl::Buffer&, cl::Buffer&> (myKernelProgram, "myKernel);
```

To invoke the kernel with enqueued input buffers inBuf1 and inBuf2 of size n and output buffer outBuf:

```c++
myKernel(cl::EnqueueArgs(cl::NDRange(n), cl::NDRange(n)), inBuf1, inBuf2, outBuf);
```

### 3.7 Events

Class `cl::Event` provides functionality for working with OpenCL events.

The method

```c++
template <typename T>
c_int cl::Event::getInfo(cl_event_info name, T * param)
```

gets specific information about the OpenCL event. Table 5.18 of the *OpenCL Specification* Version 1.2 specifies the information that can be queried. The table below lists `cl_event_info` values that differ in return type between the OpenCL C API and the OpenCL C++ API.

<table>
<thead>
<tr>
<th>cl_event_info</th>
<th>C++ return Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_EVENT_CONTEXT</td>
<td>Cl::Context</td>
</tr>
<tr>
<td>CL_EVENT_COMMAND_QUEUE</td>
<td>cl::CommandQueue</td>
</tr>
</tbody>
</table>

*Table 11: Differences in cl::Event::getInfo return type vs. OpenCL Specification table 5.18*

T is a compile time argument that is the return type for the specific information being queried. It corresponds to the values in tables 5.18.

name is an enumeration constant that identifies the event information being queried. It can be one of the values specified in table 5.18.

param is a pointer to a memory location where the appropriate values for a given name as specified in table 5.18 is returned. If param is NULL, it is ignored.

`cl::Event::getInfo` returns CL_SUCCESS on success. Otherwise, it returns:

- CL_INVALID_VALUE if name is not one of the supported values.

The method

```c++
template <cl_int name> typename detail::param_traits<detail::cl_event_info, name>::param_type
cl::Event::getInfo(void)
```
gets specific information about an OpenCL event. Table 5.18 of the *OpenCL Specification* Version 1.2 specifies the information that can be queried. The table above lists `cl_event_info` values that differ in return type between the OpenCL C API and the OpenCL C++ API.

`name` is an enumeration constant that identifies the event information being queried. It can be one of the values specified in table 5.18.

`cl::Event::getInfo` returns the appropriate value for a given `name` as specified in table 5.18.

The method

```cpp
 template <typename T>
 cl_int cl::Event::getProfilingInfo(cl_profiling_info name,
                                      T * param)
```

returns profiling information for the command associated with event. Table 5.19 of the *OpenCL Specification* Version 1.2 specifies the information that can be queried.

`T` is a compile time argument that is the return type for the specific information being queried. It corresponds to the values in tables 5.19.

`name` is an enumeration constant that identifies the profiling information being queried. It can be one of the values specified in table 5.19.

`param` is a pointer to a memory location where the appropriate values for a given `name` as specified in table 5.19 is returned. If `param` is NULL, it is ignored.

`cl::Event::getInfo` returns CL_SUCCESS on success. Otherwise, it returns:

- CL_INVALID_VALUE if `name` is not one of the supported values.

The method

```cpp
 template <cl_int name> typename
detail::param_traits<detail::cl_profiling_info, name>::param_type
 cl::Event::getProfilingInfo(void)
```

returns profiling information for the command associated with event. Table 5.19 of the *OpenCL Specification* Version 1.2 specifies the information that can be queried.

`name` is an enumeration constant that identifies the profiling information being queried. It can be one of the values specified in table 5.19.

`cl::Event::getProfilingInfo` returns the appropriate value for a given `name` as specified in table 5.19.

The method

```cpp
 cl_int cl::Event::wait(void)
```

waits on the host thread for the command associated with the particular event to complete.
**cl::Event::wait** returns CL_SUCCESS if the function was executed successfully. Otherwise, it returns one of the following errors:

- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

The method

```cpp
cl_int cl::Event::setCallback(cl_int type,
                         void (CL_CALLBACK * pfn_notify)(
                           cl_event event,
                           cl_int command_exec_status,
                           void * user_data),
                         void * user_data = NULL)
```

registers a user callback function for a specific command execution status. The registered callback function is called when the execution status of command associated with event changes to the execution status specified by `command_exec_status`.

*type* specifies the command execution status for which the callback is registered. The command execution callback mask values for which a callback can be registered are: CL_COMPLETE. There is no guarantee that the callback functions registered for various execution status values for an event is called in the exact order that the execution status of a command changes.

*pfen_notify* is the event callback function registered by the application. This callback function may be called asynchronously by the OpenCL implementation. It is the application’s responsibility to ensure that the callback function is thread-safe. The parameters to the callback function are:

- *event* is the event object for which the callback function is invoked.
- *command_exec_status* represents the execution status of command for which this callback function is invoked. Refer to table 5.15 for the command execution status values. If the callback is called as the result of the command associated with event being abnormally terminated, an appropriate error code for the error that caused the termination is passed to `command_exec_status` instead.
- *user_data* is a pointer to user supplied data.

*user_data* is passed as the *user_data* argument when *pfen_notify* is called. *user_data* can be NULL.

**cl::Event::setCallback** returns CL_SUCCESS on success. Otherwise, it returns one of the following errors:

- **CL_INVALID_VALUE** if *pfen_notify* is NULL or if `command_exec_callback_type` is not a valid command execution status.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

The static method

```cpp
static cl_int cl::Event::waitForEvents(const VECTOR_CLASS<Event>& events)
```
waits on the host thread for commands identified by event objects in `events` to complete. A command is considered complete if its execution status is `CL_COMPLETE` or a negative value. The events specified in `events` act as synchronization points.

`cl::Event::waitForEvents` returns `CL_SUCCESS` if the function was executed successfully. Otherwise, it returns one of the following errors:

- `CL_INVALID_VALUE` if `events` is of length zero.
- `CL_INVALID_CONTEXT` if events specified in `events` do not belong to the same context.
- `CL_INVALID_EVENT` if event objects specified in `events` are not valid event objects.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 3.8 User Events

Class `cl::UserEvent : public Event` provides functionality for working with OpenCL user events.

The constructor

```
class UserEvent : public Event
```

```
cl::UserEvent::UserEvent(Context& context, cl_int * err = NULL)
```

creates a user event object. User events allow applications to enqueue commands that wait on a user event to finish before the command is executed by the device.

`context` must be a valid OpenCL context.

`err` returns an appropriate error code. If `err` is NULL, no error code is returned.

`cl::UserEvent::UserEvent` returns a valid object and sets `err` to `CL_SUCCESS` if it creates the user event object successfully. Otherwise, it returns one of the following error values returned in `err`:

- `CL_INVALID_CONTEXT` if context is not a valid context.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

The method

```
cl_int cl::UserEvent::setStatus(cl_int status)
```

sets the execution status of a user event object.

`status` specifies the new execution status to be set and can be `CL_COMPLETE` or a negative integer value to indicate an error.
err returns an appropriate error code. If err is NULL, no error code is returned.

cl::UserEvent::setStatus returns CL_SUCCESS if the function was executed successfully. Otherwise, it returns one of the following errors:

- CL_INVALID_VALUE if the status is not CL_COMPLETE or a negative integer value.
- CL_INVALID_OPERATION if the status for event has already been changed by a previous call to cl::UserEvent::setStatus.
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The static method

```
static cl_int cl::UserEvent::waitForEvents(const VECTOR_CLASS<Event>& events)
```

waits on the host thread for commands identified by event objects in events to complete. A command is considered complete if its execution status is CL_COMPLETE or a negative value. The events specified in events act as synchronization points.

cl::UserEvent::waitForEvents returns CL_SUCCESS if the function was executed successfully. Otherwise, it returns one of the following errors:

- CL_INVALID_VALUE if events is of length zero.
- CL_INVALID_CONTEXT if events specified in events do not belong to the same context.
- CL_INVALID_EVENT if event objects specified in events are not valid event objects.
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

## 3.9 Command Queues

Class cl::NDRange provides functionality for working with global and local NDRanges, as described in section 5.1 of the OpenCL Specification. This is a necessary type for certain enqueue commands.

The constructor

```
class::NDRange::NDRange(::size_t size0)
```

returns a 1D range.

size0 describes the number of global or local work-items in dimension 0.

The constructor
returns a 2D range.

\(size0\) describes the number of global or local work-items in dimension 0. 
\(size1\) describes the number of global or local work-items in dimension 1.

The constructor

\[
\text{cl::NDRange}:\text{NDRange}(::\text{size}_t \ size0, \\
::\text{size}_t \ size1)
\]

returns a 3D range.

\(size0\) describes the number of global or local work-items in dimension 0. 
\(size1\) describes the number of global or local work-items in dimension 1. 
\(size2\) describes the number of global or local work-items in dimension 2.

The operator

\[
\text{operator const ::size}_t \text{cl::NDRange::*()} \text{ const}
\]

returns a pointer to an array of, 1, 2, or 3 elements of the range.

The method

\[
::\text{size}_t \text{cl::NDRange::dimensions}(\text{void})
\]

returns the number of dimensions defined in the range.

Class \text{cl::CommandQueue} provides functionality for working with OpenCL command-queues.

The constructor

\[
\text{cl::CommandQueue::CommandQueue}( \\
\text{const Context}& \text{context}, \\
\text{const Device}& \text{device}, \\
\text{cl_command_queue_properties} \text{properties} = 0, \\
\text{cl_int} \text{ * err} = \text{NULL})
\]

creates a command-queue on a specific device.

\text{device} must be a device associated with context. It can either be in the list of devices specified when context is created using \text{cl::Context::Context}.

\text{properties} specifies a list of properties for the command-queue. This is a bit-field and is described in table 5.1 of the \textit{OpenCL Specification} Version 1.1. Only command-queue properties specified in table 5.1 can be set in properties; otherwise the value specified in properties is considered to be not valid.
err returns an appropriate error code. If err is NULL, no error code is returned.

cl::CommandQueue::CommandQueue returns a valid command-queue and sets err to CL_SUCCESS if it creates the command-queue successfully. Otherwise, it returns one of the following error values returned in err:

- CL_INVALID_CONTEXT if context is not a valid context.
- CL_INVALID_DEVICE if device is not a valid device or is not associated with context.
- CL_INVALID_VALUE if values specified in properties are not valid.
- CL_INVALID_QUEUE_PROPERTIES if values specified in properties are valid but are not supported by the device.
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The method

```
template <typename T>
cl_int cl::CommandQueue::getInfo(cl_command_queue_info name,
                                  T * param)
```

gets specific information about an OpenCL command queue. Table 5.2 of the OpenCL Specification Version 1.2 specifies the information that can be queried. The table below lists cl_command_queue_info values that differ in return type between the OpenCL C API and the OpenCL C++ API.

<table>
<thead>
<tr>
<th>cl_command_queue_info</th>
<th>C++ return Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_QUEUE_CONTEXT</td>
<td>cl::Context</td>
</tr>
<tr>
<td>CL_QUEUE_DEVICE</td>
<td>cl::Device</td>
</tr>
</tbody>
</table>

Table 12: Differences in cl::CommandQueue::getInfo return type vs. OpenCL Specification table 5.2

T is a compile time argument that is the return type for the specific information being queried. It corresponds to the values in table 5.2.

name is an enumeration constant that identifies the command-queue information being queried. It can be one of the values specified in table 5.2.

param is a pointer to a memory location where the appropriate values for a given name as specified in table 5.2 is returned. If param is NULL, it is ignored.

cl::CommandQueue::getInfo returns CL_SUCCESS on success. Otherwise, it returns:

- CL_INVALID_VALUE if name is not one of the supported values.

The method

```
template <cl_int name> typename
detail::param_traits<detail::cl::command_queue_info, name>::param_type
cl::CommandQueue::getInfo(void)
```
gets specific information about the OpenCL command-queue. Table 5.2 of the OpenCL Specification Version 1.2 specifies the information that can be queried. The table above lists cl\_command\_queue\_info values that differ in return type between the OpenCL C API and the OpenCL C++ API.

\textit{name} is an enumeration constant that identifies the command-queue information being queried. It can be one of the values specified in table 5.2.

\textbf{cl::CommandQueue::getInfo} returns the appropriate value for a given \textit{name} as specified in table 5.2.

The methods

\begin{verbatim}
cl_int cl::CommandQueue::enqueueReadBuffer(    const Buffer& buffer,    cl_bool blocking_read,    ::size_t offset,    ::size_t size,    const void * ptr,    const VECTOR_CLASS<Event> * events = NULL,    Event * event = NULL)
\end{verbatim}

and

\begin{verbatim}
cl_int cl::CommandQueue::enqueueWriteBuffer(    const Buffer& buffer,    cl_bool blocking_write,    ::size_t offset,    ::size_t size,    const void * ptr,    const VECTOR_CLASS<Event> * events = NULL,    Event * event = NULL)
\end{verbatim}

enqueue a command to read from a buffer object to host memory or to write to a buffer object from host memory.

\textit{buffer} refers to a valid buffer object.

\textit{blocking\_read} and \textit{blocking\_write} indicate if the read and write operations are blocking or nonblocking.

If \textit{blocking\_read} is CL\_TRUE (i.e., the read command is blocking), \textbf{cl::CommandQueue::enqueueReadBuffer} does not return until the buffer data has been read and copied into memory pointed to by \textit{ptr}.

If \textit{blocking\_read} is CL\_FALSE (i.e., the read command is non-blocking), \textbf{cl::CommandQueue::enqueueReadBuffer} queues a non-blocking read command and returns. The contents of the buffer to which \textit{ptr} points cannot be used until the read command has completed. The event argument returns an event object which can be used to query the execution status of the read command. When the read command has completed, the contents of the buffer that \textit{ptr} points to can be used by the application.
If `blocking_write` is CL_TRUE, the OpenCL implementation copies the data referred to by `ptr` and enqueues the write operation in the command-queue. The memory pointed to by `ptr` can be reused by the application after the `cl::CommandQueue::enqueueWriteBuffer` call returns.

If `blocking_write` is CL_FALSE, the OpenCL implementation will use `ptr` to perform a nonblocking write. As the write is non-blocking the implementation can return immediately. The memory pointed to by `ptr` cannot be reused by the application after the call returns. The event argument returns an event object which can be used to query the execution status of the write command. When the write command has completed, the memory pointed to by `ptr` can then be reused by the application.

`offset` is the offset in bytes in the buffer object to read from or write to.

`size` is the size in bytes of data being read or written.

`ptr` is the pointer to buffer in host memory where data is to be read into or to be written from.

`events` is the list of events that need to complete before this particular command can be executed. If `events` is NULL or of zero length, then this particular command does not wait on any event to complete. The events specified in `events` act as synchronization points. The context associated with events in `events` and the command-queue must be the same.

`event` returns an event object that identifies this particular read / write command and can be used to query or queue a wait for this particular command to complete. `event` can be NULL, in which case it will not be possible for the application to query the status of this command or queue a wait for this command to complete.

`cl::CommandQueue::enqueueReadBuffer` and `cl::CommandQueue::enqueueWriteBuffer` return CL_SUCCESS on success. Otherwise, it returns one of the following errors:

- CL_INVALID_CONTEXT if the context associated with command-queue and buffer are not the same or if the context associated with command-queue and events in `events` are not the same.
- CL_INVALID_MEM_OBJECT if buffer is not a valid buffer object.
- CL_INVALID_VALUE if the region being read or written specified by (offset, size) is out of bounds or if `ptr` is a NULL value.
- CL_INVALID_EVENT_WAIT_LIST if event objects in `events` are not valid events.
- CL_MISALIGNED_SUB_BUFFER_OFFSET if buffer is a sub-buffer object and offset specified when the sub-buffer object is created is not aligned to CL_DEVICE_MEM_BASE_ADDR_ALIGN value for device associated with queue.
- CL_MEM_OBJECT_ALLOCATION_FAILURE if there is a failure to allocate memory for data store associated with buffer.
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The methods

```cpp
cl_int cl::CommandQueue::enqueueReadBufferRect(
    const Buffer& buffer,
    cl_bool blocking_read,
    const size_t<3> buffer_offset,
)```

const size_t<3> host_offset,
const size_t<3> region,
::size_t buffer_row_pitch,
::size_t buffer_slice_pitch,
::size_t host_row_pitch,
::size_t host_slice_pitch,
void * ptr,
const VECTOR_CLASS<Event> * events = NULL,
Event * event = NULL)

and

cl_int cl::CommandQueue::enqueueWriteBufferRect(
    const Buffer& buffer,
    cl_bool blocking_write,
    const size_t<3> & buffer_offset,
    const size_t<3> & host_offset,
    const size_t<3>& region,
    ::size_t buffer_row_pitch,
    ::size_t buffer_slice_pitch,
    ::size_t host_row_pitch,
    ::size_t host_slice_pitch,
    void * ptr,
    const VECTOR_CLASS<Event> * events = NULL,
    Event * event = NULL)

enqueue command to read a 2D or 3D rectangular region from a buffer object to host memory or write a 2D or 3D rectangular region of a buffer object from host memory.

buffer refers to a valid buffer object.

blocking_read and blocking_write indicate if the read and write operations are blocking or nonblocking.

If blocking_read is CL_TRUE (i.e., the read command is blocking),
cl::CommandQueue::enqueueReadBufferRect does not return until the buffer data has been read and copied into memory pointed to by ptr.

If blocking_read is CL_FALSE (i.e., the read command is non-blocking),
cl::CommandQueue::enqueueReadBufferRect queues a non-blocking read command and returns. The contents of the buffer that ptr points to cannot be used until the read command has completed. The event argument returns an event object which can be used to query the execution status of the read command. When the read command has completed, the contents of the buffer that ptr points to can be used by the application.

If blocking_write is CL_TRUE, the OpenCL implementation copies the data referred to by ptr and enqueues the write operation in the command-queue. The memory pointed to by ptr can be reused by the application after the cl::CommandQueue::enqueueWriteBufferRect call returns.

If blocking_write is CL_FALSE, the OpenCL implementation will use ptr to perform a nonblocking write. As the write is non-blocking the implementation can return immediately. The memory pointed to by ptr cannot be reused by the application after the call returns. The event argument returns an event object which can be used to
query the execution status of the write command. When the write command has completed, the memory pointed to by \texttt{ptr} can then be reused by the application.

\textit{buffer\_origin} defines the \((x, y, z)\) offset in the memory region associated with buffer. For a 2D rectangle region, the \(z\) value given by \texttt{buffer\_origin[2]} should be 0. The offset in bytes is computed as \(\texttt{buffer\_origin[2]} \times \texttt{buffer\_slice\_pitch} + \texttt{buffer\_origin[1]} \times \texttt{buffer\_row\_pitch} + \texttt{buffer\_origin[0]}\).

\textit{host\_origin} defines the \((x, y, z)\) offset in the memory region pointed to by \texttt{ptr}. For a 2D rectangle region, the \(z\) value given by \texttt{host\_origin[2]} should be 0. The offset in bytes is computed as \(\texttt{host\_origin[2]} \times \texttt{host\_slice\_pitch} + \texttt{host\_origin[1]} \times \texttt{host\_row\_pitch} + \texttt{host\_origin[0]}\).

\textit{region} defines the \((width, height, depth)\) in bytes of the 2D or 3D rectangle being read or written. For a 2D rectangle copy, the depth value given by \texttt{region[2]} should be 1.

\textit{buffer\_row\_pitch} is the length of each row in bytes to be used for the memory region associated with buffer. If \texttt{buffer\_row\_pitch} is 0, \texttt{buffer\_row\_pitch} is computed as \texttt{region[0]}.

\textit{buffer\_slice\_pitch} is the length of each 2D slice in bytes to be used for the memory region associated with buffer. If \texttt{buffer\_slice\_pitch} is 0, \texttt{buffer\_slice\_pitch} is computed as \texttt{region[1]} \times \texttt{buffer\_row\_pitch}.

\textit{host\_row\_pitch} is the length of each row in bytes to be used for the memory region pointed to by \texttt{ptr}. If \texttt{host\_row\_pitch} is 0, \texttt{host\_row\_pitch} is computed as \texttt{region[0]}.

\textit{host\_slice\_pitch} is the length of each 2D slice in bytes to be used for the memory region pointed to by \texttt{ptr}. If \texttt{host\_slice\_pitch} is 0, \texttt{host\_slice\_pitch} is computed as \texttt{region[1]} \times \texttt{host\_row\_pitch}.

\texttt{ptr} is the pointer to buffer in host memory where data is to be read into or to be written from.

\textit{events} specifies the events that need to complete before this particular command can be executed. If \texttt{events} is NULL or of zero length, then this particular command does not wait on any event to complete. If \texttt{events} is not NULL and non-zero length, the list of events must be valid. The events specified in \texttt{events} act as synchronization points. The context associated with events in \texttt{events} and the command-queue must be the same.

\textit{event} returns an event object that identifies this particular read / write command and can be used to query or queue a wait for this particular command to complete. \texttt{event} can be NULL, in which case it will not be possible for the application to query the status of this command or queue a wait for this command to complete.

\texttt{cl\::CommandQueue::enqueueReadBufferRect} and \texttt{cl\::CommandQueue::enqueueWrite BufferRect} return \texttt{CL\_SUCCESS} on success. Otherwise, it returns one of the following errors:

- \texttt{CL\_INVALID\_CONTEXT} if the context associated with command-queue and \texttt{buffer} are not the same or if the context associated with command-queue and events in \texttt{events} are not the same.
- \texttt{CL\_INVALID\_MEM\_OBJECT} if buffer is not a valid buffer object.
- \texttt{CL\_INVALID\_VALUE} if the region being read or written specified by \((\texttt{buffer\_offset, region})\) is out of bounds.
- \texttt{CL\_INVALID\_VALUE} if \texttt{ptr} is a NULL value.
- \texttt{CL\_INVALID\_EVENT\_WAIT\_LIST} if event objects in \texttt{events} are not valid events.
- CL_MISALIGNED_SUB_BUFFER_OFFSET if buffer is a sub-buffer object and offset specified when the sub-buffer object is created is not aligned to CL_DEVICE_MEM_BASE_ADDR_ALIGN value for device associated with queue.
- CL_MEM_OBJECT_ALLOCATION_FAILURE if there is a failure to allocate memory for data store associated with buffer.
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The method

```cpp
cl_int cl::CommandQueue::enqueueCopyBuffer(
    const Buffer & src,
    const Buffer & dst,
    ::size_t src_offset,
    ::size_t dst_offset,
    ::size_t size,
    const VECTOR_CLASS<Event> * events = NULL,
    Event * event = NULL)
```

enqueues a command to copy a buffer object identified by `src` to another buffer object identified by `dst`. The OpenCL context associated with command-queue, `src` and `dst` must be the same.

`src` refers to the offset where to begin copying data from `src`.

`dst` refers to the offset where to begin copying data into `dst`.

`size` refers to the size in bytes to copy.

`events` specifies events that need to complete before this particular command can be executed. If `events` is NULL or of length zero, then this particular command does not wait on any event to complete. If `events` is not NULL and a nonzero length, the list of events pointed to by `events` must be valid. The events specified in `events` act as synchronization points. The context associated with events in `events` and the command-queue must be the same.

`event` returns an event object that identifies this particular copy command and can be used to query or queue a wait for this particular command to complete. `event` can be NULL, in which case it will not be possible for the application to query the status of this command or queue a wait for this command to complete. `cl::CommandQueue::enqueueBarrier` can be used instead.

`cl::CommandQueue::enqueueCopyBuffer` returns CL_SUCCESS on success. Otherwise, it returns one of the following errors:

- CL_INVALID_CONTEXT if the context associated with the command-queue, `src` and `dst` are not the same or if the context associated with the command-queue and events in `events` are not the same.
- CL_INVALID_MEM_OBJECT if `src` and `dst` are not valid buffer objects.
- CL_INVALID_VALUE if `src`, `dst`, `size`, `src + size` or `dst + size` require accessing elements outside the `src` and `dst` buffer objects respectively.
- CL_INVALID_EVENT_WAIT_LIST if event objects in `events` are not valid events.
• CL_MISALIGNED_SUB_BUFFER_OFFSET if src is a sub-buffer object and offset specified when the sub-buffer object is created is not aligned to CL_DEVICE_MEM_BASE_ADDR_ALIGN value for device associated with queue.

• CL_MISALIGNED_SUB_BUFFER_OFFSET if dst is a sub-buffer object and offset specified when the sub-buffer object is created is not aligned to CL_DEVICE_MEM_BASE_ADDR_ALIGN value for device associated with queue.

• CL_MEM_COPY_OVERLAP if src and dst are the same buffer object and the source and destination regions overlap.

• CL_MEM_OBJECT_ALLOCATION_FAILURE if there is a failure to allocate memory for data store associated with src or dst.

• CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.

• CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The method

```cpp
cl_int cl::CommandQueue::enqueueCopyBufferRect(
    const Buffer& src_buffer,
    const Buffer& dst_buffer,
    const size_t<3>& src_origin,
    const size_t<3>& dst_origin,
    const size_t<3>& region,
    ::size_t src_row_pitch,
    ::size_t src_slice_pitch,
    ::size_t dst_row_pitch,
    ::size_t dst_slice_pitch,
    const VECTOR_CLASS<Event> * events = NULL,
    Event * event = NULL)
```
enqueues a command to copy a 2D or 3D rectangular region from the buffer object identified by src to a 2D or 3D region in the buffer object identified by dst. The OpenCL context associated with the command-queue, src and dst must be the same.

src_origin defines the (x, y, z) offset in the memory region associated with src_buffer. For a 2D rectangle region, the z value given by src_origin[2] should be 0. The offset in bytes is computed as src_origin[2] * src_slice_pitch + src_origin[1] * src_row_pitch + src_origin[0].

dst_origin defines the (x, y, z) offset in the memory region associated with dst_buffer. For a 2D rectangle region, the z value given by dst_origin[2] should be 0. The offset in bytes is computed as dst_origin[2] * dst_slice_pitch + dst_origin[1] * dst_row_pitch + dst_origin[0].

region defines the (width, height, depth) in bytes of the 2D or 3D rectangle being copied. For a 2D rectangle, the depth value given by region[2] should be 1.

src_row_pitch is the length of each row in bytes to be used for the memory region associated with src_buffer. If src_row_pitch is 0, src_row_pitch is computed as region[0].
**src_slice_pitch** is the length of each 2D slice in bytes to be used for the memory region associated with **src_buffer**. If **src_slice_pitch** is 0, **src_slice_pitch** is computed as **region[1] * src_row_pitch**.

**dst_row_pitch** is the length of each row in bytes to be used for the memory region associated with **dst_buffer**. If **dst_row_pitch** is 0, **dst_row_pitch** is computed as **region[0]**.

**dst_slice_pitch** is the length of each 2D slice in bytes to be used for the memory region associated with **dst_buffer**. If **dst_slice_pitch** is 0, **dst_slice_pitch** is computed as **region[1] * dst_row_pitch**.

**events** specifies events that need to complete before this particular command can be executed. If **events** is NULL or of length zero, then this particular command does not wait on any event to complete. If **events** is not NULL and a nonzero length, the list of events pointed to by **events** must be valid. The events specified in **events** act as synchronization points. The context associated with events in **events** and the command-queue must be the same.

**event** returns an event object that identifies this particular copy command and can be used to query or queue a wait for this particular command to complete. **event** can be NULL, in which case it will not be possible for the application to query the status of this command or queue a wait for this command to complete.

**cl::CommandQueue::enqueueCopyBufferRect** returns CL_SUCCESS on success. Otherwise, it returns one of the following errors:

- CL_INVALID_CONTEXT if the context associated with the command-queue, **src_buffer** and **dst_buffer** are not the same or if the context associated with the command-queue and events in **events** are not the same.
- CL_INVALID_MEM_OBJECT if **src_buffer** and **dst_buffer** are not valid buffer objects.
- CL_INVALID_VALUE if (**src_offset**, **region**) or (**dst_offset**, **region**) require accessing elements outside the **src_buffer** and **dst_buffer** buffer objects respectively.
- CL_INVALID_EVENT_WAIT_LIST if event objects in **events** are not valid events.
- CL_MISALIGNED_SUB_BUFFER_OFFSET if **src_buffer** is a sub-buffer object and offset specified when the sub-buffer object is created is not aligned to CL_DEVICE_MEM_BASE_ADDR_ALIGN value for device associated with queue.
- CL_MISALIGNED_SUB_BUFFER_OFFSET if **dst_buffer** is a sub-buffer object and offset specified when the sub-buffer object is created is not aligned to CL_DEVICE_MEM_BASE_ADDR_ALIGN value for device associated with queue.
- CL_MEM_COPY_OVERLAP if **src_buffer** and **dst_buffer** are the same buffer object and the source and destination regions overlap.
- CL_MEM_OBJECT_ALLOCATION_FAILURE if there is a failure to allocate memory for data store associated with **src_buffer** or **dst_buffer**.
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The method

```cpp
template<typename PatternType>
cl_int cl::CommandQueue::enqueueFillBuffer(const Buffer& buffer,
```
enqueue a command to fill a buffer object with a pattern of a given size.

**PatternType** must be an OpenCL data type.

*buffer* specifies the buffer to be filled.

*pattern* specifies the pattern.

*offset* specifies the offset into the buffer where filling begins.

*size* specifies the size of the pattern.

*events* specifies events that need to complete before this particular command can be executed. If *events* is NULL or of length zero, then this particular command does not wait on any event to complete. If *events* is not NULL and a nonzero length, the list of events pointed to by *events* must be valid. The events specified in *events* act as synchronization points. The context associated with events in *events* and the command-queue must be the same.

*event* returns an event object that identifies this particular copy command and can be used to query or queue a wait for this particular command to complete. *event* can be NULL, in which case it will not be possible for the application to query the status of this command or queue a wait for this command to complete.

**cl::CommandQueue::enqueueFillBuffer** returns **CL_SUCCESS** on success.

The methods

```cpp
cl_int cl::CommandQueue::enqueueReadImage(
    const Image& image,
    cl_bool blocking_read,
    const size_t<3>& origin,
    const size_t<3>& region,
    ::size_t row_pitch,
    ::size_t slice_pitch,
    void *ptr,
    const VECTOR_CLASS<Event>* events = NULL,
    Event* event = NULL)
```

and

```cpp
cl_int cl::CommandQueue::enqueueWriteImage(
    const Image& image,
    cl_bool blocking_write,
    const size_t<3>& origin,
    const size_t<3>& region,
    ::size_t row_pitch,
    ::size_t slice_pitch,
    void *ptr,
    const VECTOR_CLASS<Event>* events = NULL,
    Event* event = NULL)
```
::size_t row_pitch,
::size_t slice_pitch,
const void * ptr,
const VECTOR_CLASS<Event> * events = NULL,
Event * event = NULL)

enqueues commands to read from a 2D or 3D image object to host memory or write to a 2D or 3D image object from host memory.

image refers to a valid 2D or 3D image object.

blocking_read and blocking_write indicate if the read and write operations are blocking or nonblocking.

If blocking_read is CL_TRUE (i.e., the read command is blocking),
cl::CommandQueue::enqueueReadImage does not return until the buffer data has been read and copied into memory pointed to by ptr.

If blocking_read is CL_FALSE (i.e., the read command is non-blocking),
cl::CommandQueue::enqueueReadImage queues a non-blocking read command and returns. The contents of the buffer to which ptr points cannot be used until the read command has completed. The event argument returns an event object that can be used to query the execution status of the read command. When the read command has completed, the contents of the buffer that ptr points to can be used by the application.

If blocking_write is CL_TRUE, the OpenCL implementation copies the data referred to by ptr and enqueues the write command in the command-queue. The memory pointed to by ptr can be reused by the application after the cl::CommandQueue::enqueueWriteImage call returns.

If blocking_write is CL_FALSE, the OpenCL implementation will use ptr to perform a nonblocking write. As the write is non-blocking the implementation can return immediately. The memory pointed to by ptr cannot be reused by the application after the call returns. The event argument returns an event object which can be used to query the execution status of the write command. When the write command has completed, the memory pointed to by ptr can then be reused by the application.

origin defines the (x, y, z) offset in pixels in the image from where to read or write. If image is a 2D image object, the z value given by origin[2] must be 0.

region defines the (width, height, depth) in pixels of the 2D or 3D rectangle being read or written. If image is a 2D image object, the depth value given by region[2] must be 1.

row_pitch in cl::CommandQueue::enqueueReadImage and input_row_pitch in cl::CommandQueue::enqueueWriteImage is the length of each row in bytes. This value must be greater than or equal to the element size in bytes * width. If row_pitch (or input_row_pitch) is set to 0, the appropriate row pitch is calculated based on the size of each element in bytes multiplied by width.

slice_pitch in cl::CommandQueue::enqueueReadImage and input_slice_pitch in cl::CommandQueue::enqueueWriteImage is the size in bytes of the 2D slice of the 3D region of a 3D image being read or written respectively. This must be 0 if image is a 2D image. This value must be greater than or equal to row_pitch * height. If slice_pitch (or input_slice_pitch) is set to 0, the appropriate slice pitch is calculated based on the row_pitch * height.
ptr is the pointer to a buffer in host memory where image data is to be read from or to be written to.

events specifies events that need to complete before this particular command can be executed. If events is NULL or of length zero, then this particular command does not wait on any event to complete. If events is not NULL and of nonzero length, the list of events pointed to by events must be valid. The events specified in events act as synchronization points. The context associated with events in events and the command-queue must be the same.

event returns an event object that identifies this particular copy command and can be used to query or queue a wait for this particular command to complete. event can be NULL, in which case it will not be possible for the application to query the status of this command or queue a wait for this command to complete.

cl::CommandQueue::enqueueReadImage and cl::CommandQueue::enqueueWriteImage return CL_SUCCESS on success. Otherwise, it returns one of the following errors:

- CL_INVALID_CONTEXT if the context associated with the command-queue and image are not the same or if the context associated with the command-queue and events in events are not the same.
- CL_INVALID_MEM_OBJECT if image is not a valid image object.
- CL_INVALID_VALUE if the region being read or written specified by origin and region is out of bounds or if ptr is a NULL value.
- CL_INVALID_VALUE if image is a 2D image object and origin[2] is not equal to 0 or region[2] is not equal to 1 or slice_pitch is not equal to 0.
- CL_INVALID_EVENT_WAIT_LIST if event objects in events are not valid events.
- CL_INVALID_IMAGE_SIZE if image dimensions (image width, height, specified or compute row and/or slice pitch) for image are not supported by device associated with queue.
- CL_MEM_OBJECT_ALLOCATION_FAILURE if there is a failure to allocate memory for data store associated with image.
- CL_INVALID_OPERATION if the device associated with the command-queue does not support images (i.e., CL_DEVICE_IMAGE_SUPPORT specified in table 4.3 is CL_FALSE).
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The method

```c
cl_int cl::CommandQueue::enqueueCopyImage(
    const Image& src_image,
    const Image& dst_image,
    const size_t <3>& src_origin,
    const size_t <3>& dst_origin,
    const size_t<3>& region,
    const VECTOR_CLASS<Event> * events = NULL,
    Event * event = NULL)
```

enqueues a command to copy image objects.

src_image and dst_image can be 2D or 3D image objects allowing us to perform the following actions:

- Copy a 2D image object to a 2D image object.
- Copy a 2D image object to a 2D slice of a 3D image object.
- Copy a 2D slice of a 3D image object to a 2D image object.
- Copy a 3D image object to a 3D image object.

The OpenCL context associated with command-queue, `src_image` and `dst_image` must be the same.

`src_origin` defines the starting (x, y, z) location in pixels in `src_image` from where to start the data copy. If `src_image` is a 2D image object, the z value given by `src_origin[2]` must be 0.

`dst_origin` defines the starting (x, y, z) location in pixels in `dst_image` from where to start the data copy. If `dst_image` is a 2D image object, the z value given by `dst_origin[2]` must be 0

`region` defines the (width, height, depth) in pixels of the 2D or 3D rectangle to copy. If `src_image` or `dst_image` is a 2D image object, the depth value given by `region[2]` must be 1.

`events` specifies events that need to complete before this particular command can be executed. If `events` is NULL or of length zero, then this particular command does not wait on any event to complete. If `events` is not NULL and a nonzero length, the list of events pointed to by `events` must be valid. The events specified in `events` act as synchronization points. The context associated with events in `events` and the command-queue must be the same.

`event` returns an event object that identifies this particular copy command and can be used to query or queue a wait for this particular command to complete. `event` can be NULL, in which case it will not be possible for the application to query the status of this command or queue a wait for this command to complete.

It is currently a requirement that the `src_image` and `dst_image` image memory objects for `cl::CommandQueue::enqueueCopyImage` must have the exact same image format (i.e., the `cl_image_format` descriptor specified when `src_image` and `dst_image` are created must match).

`cl::CommandQueue::enqueueCopyImage` returns CL_SUCCESS on success. Otherwise, it returns one of the following errors:

- CL_INVALID_CONTEXT if the context associated with the command-queue, `src_image` and `dst_image` are not the same or if the context associated with the command-queue and events in `events` are not the same.
- CL_INVALID_MEM_OBJECT if `src_image` and `dst_image` are not valid image objects.
- CL_IMAGE_FORMAT_MISMATCH if `src_image` and `dst_image` do not use the same image format.
- CL_INVALID_VALUE if the 2D or 3D rectangular region specified by `src_origin` and `src_origin + region` refers to a region outside `src_image`, or if the 2D or 3D rectangular region specified by `dst_origin` and `dst_origin + region` refers to a region outside `dst_image`.
- CL_INVALID_VALUE if `src_image` is a 2D image object and `src_origin[2]` is not equal to 0 or `region[2]` is not equal to 1.
- CL_INVALID_VALUE if `dst_image` is a 2D image object and `dst_origin[2]` is not equal to 0 or `region[2]` is not equal to 1.
- CL_INVALID_EVENT_WAIT_LIST if event objects in `events` are not valid events.
- CL_INVALID_IMAGE_SIZE if image dimensions (image width, height, specified or compute row and/or slice pitch) for `src_image` are not supported by device associated with queue.
- CL_INVALID_IMAGE_SIZE if image dimensions (image width, height, specified or compute row and/or slice pitch) for `dst_image` are not supported by device associated with queue.
• CL_MEM_OBJECT_ALLOCATION_FAILURE if there is a failure to allocate memory for data store associated with \texttt{src\_image} or \texttt{dst\_image}.
• CL\_OUT\_OF\_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
• CL\_OUT\_OF\_HOST\_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The method

\begin{verbatim}
cl\_int cl::CommandQueue::enqueueFillImage(const Image& image,  
  cl\_float4 fillColor,  
  const size\_t<3>& origin,  
  const size\_t<3>& region,  
  const VECTOR\_CLASS<Event> * events = NULL,  
  Event * event = NULL)
\end{verbatim}

enqueues a command to fill an image object with a given fill color.

\textit{image} is a valid image object.

\textit{fill\_color} is the four component RGBA fill color.

\textit{origin} defines the (x, y, z) offset in pixels in the image to fill. If \textit{image} is a 2D image object, the z value given by \textit{origin}[2] must be 0.

\textit{region} defines the (width, height, depth) in pixels of the 2D or 3D rectangle to fill. If \textit{image} is a 2D image object, the depth value given by \textit{region}[2] must be 1.

\textit{events} specifies events that need to complete before this particular command can be executed. If \textit{events} is NULL or of length zero, then this particular command does not wait on any event to complete. If \textit{events} is not NULL and a nonzero length, the list of events pointed to by \textit{events} must be valid. The events specified in \textit{events} act as synchronization points. The context associated with events in \textit{events} and the command-queue must be the same.

\textit{event} returns an event object that identifies this particular copy command and can be used to query or queue a wait for this particular command to complete. \textit{event} can be NULL, in which case it will not be possible for the application to query the status of this command or queue a wait for this command to complete.

\textit{cl::CommandQueue::enqueueFillImage} returns CL\_SUCCESS on success.

The method

\begin{verbatim}
cl\_int cl::CommandQueue::enqueueCopyImageToBuffer(  
  const Image& src\_image,  
  const Buffer& dst\_buffer,  
  const size\_t<3>& src\_origin,  
  const size\_t<3>& region,  
  const ::size\_t dst\_offset,  
  const VECTOR\_CLASS<Event> * events = NULL,
\end{verbatim}

enqueues a command to copy an image object to a buffer object. The OpenCL context associated with the command-queue, \textit{src\_image} and \textit{dst\_buffer} must be the same.

\textit{src\_image} is a valid image object.

\textit{dst\_buffer} is a valid buffer object.

\textit{src\_origin} defines the (x, y, z) offset in pixels in the image from where to copy. If \textit{src\_image} is a 2D image object, the z value given by \textit{src\_origin}[2] must be 0.

\textit{region} defines the (width, height, depth) in pixels of the 2D or 3D rectangle to copy. If \textit{src\_image} is a 2D image object, the depth value given by \textit{region}[2] must be 1.

\textit{dst\_offset} refers to the offset where to begin copying data into \textit{dst\_buffer}. The size in bytes of the region to be copied referred to as \textit{dst\_cb} is computed as width \* height \* depth \* bytes/image element if \textit{src\_image} is a 3D image object and is computed as width \* height \* bytes/image element if \textit{src\_image} is a 2D image object.

\textit{events} specifies events that need to complete before this particular command can be executed. If \textit{events} is NULL or of length zero, then this particular command does not wait on any event to complete. If \textit{events} is not NULL and a nonzero length, the list of events pointed to by \textit{events} must be valid. The events specified in \textit{events} act as synchronization points. The context associated with events in \textit{events} and the command-queue must be the same.

\textit{event} returns an event object that identifies this particular copy command and can be used to query or queue a wait for this particular command to complete. \textit{event} can be NULL, in which case it will not be possible for the application to query the status of this command or queue a wait for this command to complete.

\texttt{cl::CommandQueue::enqueueCopyImageToBuffer} returns CL\_SUCCESS on success. Otherwise, it returns one of the following errors:

- CL\_INVALID\_CONTEXT if the context associated with the command-queue, \textit{src\_image} and \textit{dst\_buffer} are not the same or if the context associated with the command-queue and events in \textit{events} are not the same.
- CL\_INVALID\_MEM\_OBJECT if \textit{src\_image} is not a valid image object or \textit{dst\_buffer} is not a valid buffer object.
- CL\_INVALID\_VALUE if the 2D or 3D rectangular region specified by \textit{src\_origin} and \textit{src\_origin} + \textit{region} refers to a region outside \textit{src\_image}, or if the region specified by \textit{dst\_offset} and \textit{dst\_offset} + \textit{dst\_cb} to a region outside \textit{dst\_buffer}.
- CL\_INVALID\_VALUE if \textit{src\_image} is a 2D image object and \textit{src\_origin}[2] is not equal to 0 or \textit{region}[2] is not equal to 1.
- CL\_INVALID\_EVENT\_WAIT\_LIST if event objects in \textit{events} are not valid events.
- CL\_MISALIGNED\_SUB\_BUFFER\_OFFSET if \textit{dst\_buffer} is a sub-buffer object and offset specified when the sub-buffer object is created is not aligned to CL\_DEVICE\_MEM\_BASE\_ADDR\_ALIGN value for device associated with queue. CL\_INVALID\_IMAGE\_SIZE if image dimensions (image width, height, specified or compute row and/or slice pitch) for \textit{src\_image} are not supported by device associated with queue.
- CL\_MEM\_OBJECT\_ALLOCATION\_FAILURE if there is a failure to allocate memory for data store associated with \textit{src\_image} or \textit{dst\_buffer}.
- CL_INVALID_OPERATION if the device associated with the command-queue does not support images (i.e., CL_DEVICE_IMAGE_SUPPORT specified in table 4.3 is CL_FALSE).
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The method

```cpp
cl_int cl::CommandQueue::enqueueCopyBufferToImage(
    const Buffer& src_buffer,
    const Image& dst_image,
    const ::size_t src_offset,
    const size_t<3>& dst_origin,
    const size_t<3>& region,
    const VECTOR_CLASS<Event> * events = NULL,
    Event * event = NULL)
```

enqueues a command to copy a buffer object to an image object. The OpenCL context associated with the command-queue, `src_buffer` and `dst_image` must be the same.

`src_buffer` is a valid buffer object.

`dst_image` is a valid image object.

`src_offset` refers to the offset where to begin copying data from `src_buffer`.

`dst_origin` refers to the (x, y, z) offset in pixels where to begin copying data to `dst_image`. If `dst_image` is a 2D image object, the z value given by `dst_origin[2]` must be 0.

`region` defines the (width, height, depth) in pixels of the 2D or 3D rectangle to copy. If `dst_image` is a 2D image object, the depth value given by `region[2]` must be 1. The size in bytes of the region to be copied from `src_buffer` referred to as `src_cb` is computed as width * height * depth * bytes/image element if `dst_image` is a 3D image object and is computed as width * height * bytes/image element if `dst_image` is a 2D image object.

`events` specifies events that need to complete before this particular command can be executed. If `events` is NULL or of length zero, then this particular command does not wait on any event to complete. If `events` is not NULL and a nonzero length, the list of events pointed to by `events` must be valid. The events specified in `events` act as synchronization points. The context associated with events in `events` and the command-queue must be the same.

`event` returns an event object that identifies this particular copy command and can be used to query or queue a wait for this particular command to complete. `event` can be NULL, in which case it will not be possible for the application to query the status of this command or queue a wait for this command to complete.

`cl::CommandQueue::enqueueCopyBufferToImage` returns CL_SUCCESS on success. Otherwise, it returns one of the following errors:

- CL_INVALID_CONTEXT if the context associated with the command-queue, `src_buffer` and `dst_image` are not the same or if the context associated with the command-queue and events in `events` are not the same.
• CL_INVALID_MEM_OBJECT if `src_buffer` is not a valid buffer object or `dst_image` is not a valid image object.
• CL_INVALID_VALUE if the 2D or 3D rectangular region specified by `dst_origin` and `dst_origin + region` refer to a region outside `dst_image`, or if the region specified by `src_offset` and `src_offset + src_cb` refer to a region outside `src_buffer`.
• CL_INVALID_EVENT_WAIT_LIST if event objects in `events` are not valid events.
• CL_MISALIGNED_SUB_BUFFER_OFFSET if `src_buffer` is a sub-buffer object and offset specified when the sub-buffer object is created is not aligned to CL_DEVICE_MEM_BASE_ADDR_ALIGN value for device associated with queue. CL_INVALID_IMAGE_SIZE if image dimensions (image width, height, specified or compute row and/or slice pitch) for `dst_image` are not supported by device associated with queue.
• CL_MEM_OBJECT_ALLOCATION_FAILURE if there is a failure to allocate memory for data store associated with `src_buffer` or `dst_image`.
• CL_INVALID_OPERATION if the device associated with the command-queue does not support images (i.e., CL_DEVICE_IMAGE_SUPPORT specified in table 4.3 is CL_FALSE).
• CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
• CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The method

```cpp
void * cl::CommandQueue::enqueueMapBuffer(
    const Buffer& buffer,
    cl_bool blocking_map,
    cl_map_map_flags,
    ::size_t offset,
    ::size_t size,
    const VECTOR_CLASS<Event> * events = NULL,
    Event * event = NULL,
    cl_int * err = NULL)
```

enqueues a command to map a region of the buffer object given by `buffer` into the host address space and returns a pointer to this mapped region.

`blocking_map` indicates if the map operation is blocking or non-blocking.

If `blocking_map` is CL_TRUE, `cl::CommandQueue::enqueueMapBuffer` does not return until the specified region in `buffer` can be mapped.

If `blocking_map` is CL_FALSE (i.e., the map operation is non-blocking), the pointer to the mapped region returned by `cl::CommandQueue::enqueueMapBuffer` cannot be used until the map command has completed. The `event` argument returns an event object that can be used to query the execution status of the map command. When the map command is completed, the application can access the contents of the mapped region using the pointer returned by `cl::CommandQueue::enqueueMapBuffer`.

`map_flags` is a bit-field and can be set to CL_MAP_READ to indicate that the region specified by `(offset, size)` in the buffer object is being mapped for reading, and/or CL_MAP_WRITE to indicate that the region specified by `(offset, size)` in the buffer object is being mapped for writing.
buffer is a valid buffer object. The OpenCL context associated with command_queue and buffer must be the same.

offset and size are the offset in bytes and the size of the region in the buffer object that is being mapped.

events specifies events that need to complete before this particular command can be executed. If events is NULL or of length zero, then this particular command does not wait on any event to complete. If events is not NULL and a nonzero length, the list of events pointed to by events must be valid. The events specified in events act as synchronization points. The context associated with events in events and the command-queue must be the same.

event returns an event object that identifies this particular copy command and can be used to query or queue a wait for this particular command to complete. event can be NULL, in which case it will not be possible for the application to query the status of this command or queue a wait for this command to complete.

er returns an appropriate error code. If err is NULL, no error code is returned.

cl::CommandQueue::enqueueMapBuffer returns a pointer to the mapped region and sets err to CL_SUCCESS on success.

A NULL pointer is returned otherwise with one of the following error values returned in err:

- CL_INVALID_CONTEXT if context associated with the command queue and buffer are not the same or if the context associated with the command queue and events in events are not the same.
- CL_INVALID_MEM_OBJECT if buffer is not a valid buffer object.
- CL_INVALID_VALUE if region being mapped given by (offset, size) is out of bounds or if values specified in map_flags are not valid.
- CL_INVALID_EVENT_WAIT_LIST if event objects in events are not valid events.
- CL_MISALIGNED_SUB_BUFFER_OFFSET if buffer is a sub-buffer object and offset specified when the sub-buffer object is created is not aligned to CL_DEVICE_MEM_BASE_ADDR_ALIGN value for device associated with queue.
- CL_MAP_FAILURE if there is a failure to map the requested region into the host address space. This error cannot occur for buffer objects created with CL_MEM_USE_HOST_PTR or CL_MEM_ALLOC_HOST_PTR.
- CL_MEM_OBJECT_ALLOCATION_FAILURE if there is a failure to allocate memory for data store associated with buffer.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The pointer returned maps a region starting at offset and is at least size bytes in size. The result of a memory access outside this region is undefined.

The method

```cpp
void * cl::CommandQueue::enqueueMapImage(
        const Buffer& image,
        cl_bool blocking_map,
        cl_map_map_flags,
        ::size_t<3>& origin,
        ::size_t<3>& region,
```
::size_t * row_pitch,
::size_t * slice_pitch,
const VECTOR_CLASS<Event> * events = NULL,
Event * event = NULL,
cl_int * err = NULL)

cl::CommandQueue::enqueueMapImage

enqueues a command to map a region in the image object given by image into the host address space and returns a pointer to this mapped region.

image is a valid image object. The OpenCL context associated with the command queue and image must be the same.

blocking_map indicates if the map operation is blocking or non-blocking.

If blocking_map is CL_TRUE, cl::CommandQueue::enqueueMapImage does not return until the specified region in image is mapped.

If blocking_map is CL_FALSE (i.e., the map operation is non-blocking), the pointer to the mapped region returned by cl::CommandQueue::enqueueMapImage cannot be used until the map command has completed. The event argument returns an event object that can be used to query the execution status of the map command. When the map command is completed, the application can access the contents of the mapped region using the pointer returned by cl::CommandQueue::enqueueMapImage.

map_flags is a bit-field and can be set to CL_MAP_READ to indicate that the region specified by (origin, region) in the image object is being mapped for reading, and/or CL_MAP_WRITE to indicate that the region specified by (origin, region) in the image object is being mapped for writing.

origin and region define the (x, y, z) offset in pixels and (width, height, depth) in pixels of the 2D or 3D rectangle region that is to be mapped. If image is a 2D image object, the z value given by origin[2] must be 0 and the depth value given by region[2] must be 1.

row_pitch returns the scan-line pitch in bytes for the mapped region. This must be a non-NULL value.

slice_pitch returns the size in bytes of each 2D slice for the mapped region. For a 2D image, zero is returned if this argument is not NULL. For a 3D image, slice_pitch must be a non-NULL value.

events specifies events that need to complete before this particular command can be executed. If events is NULL or of length zero, then this particular command does not wait on any event to complete. If events is not NULL and a nonzero length, the list of events pointed to by events must be valid. The events specified in events act as synchronization points. The context associated with events in events and the command-queue must be the same.

event returns an event object that identifies this particular copy command and can be used to query or queue a wait for this particular command to complete. event can be NULL, in which case it will not be possible for the application to query the status of this command or queue a wait for this command to complete.

err returns an appropriate error code. If err is NULL, no error code is returned.

cl::CommandQueue::enqueueMapImage returns a pointer to the mapped region and sets err to
CL_SUCCESS on success. It returns NULL otherwise, with one of the following error values returned in `err`:

- **CL_INVALID_CONTEXT** if context associated with the `command queue` and `image` are not the same or if context associated with the `command queue` and events in `events` are not the same.
- **CL_INVALID_MEM_OBJECT** if `image` is not a valid image object.
- **CL_INVALID_VALUE** if region being mapped given by `(origin, origin+region)` is out of bounds or if values specified in `map_flags` are not valid.
- **CL_INVALID_VALUE** if `image` is a 2D image object and `origin[2]` is not equal to 0 or `region[2]` is not equal to 1.
- **CL_INVALID_VALUE** if `row_pitch` is NULL.
- **CL_INVALID_VALUE** if `image` is a 3D image object and `slice_pitch` is NULL.
- **CL_INVALID_EVENT_WAIT_LIST** if event objects in `events` are not valid events.
- **CL_INVALID_IMAGE_SIZE** if image dimensions (image width, height, specified or compute row and/or slice pitch) for `image` are not supported by device associated with `queue`.
- **CL_MAP_FAILURE** if there is a failure to map the requested region into the host address space. This error cannot occur for image objects created with CL_MEM_USE_HOST_PTR or CL_MEM_ALLOC_HOST_PTR.
- **CL_MEM_OBJECT_ALLOCATION_FAILURE** if there is a failure to allocate memory for data store associated with `buffer`.
- **CL_INVALID_OPERATION** if the device associated with the `command queue` does not support images (i.e., CL_DEVICE_IMAGE_SUPPORT specified in table 4.3 is CL_FALSE).
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

The pointer returned maps a 2D or 3D region starting at `origin` and is at least `(row_pitch * region[1] + region[0])` pixels in size for a 2D image, and is at least `(slice_pitch * region[2] + row_pitch * region[1] + region[0])` pixels in size for a 3D image. The result of a memory access outside this region is undefined.

If the image object is created with CL_MEM_USE_HOST_PTR set in `mem_flags`, the following will be true:

- The `host_ptr` specified in `cl::Image{2D|3D}` is guaranteed to contain the latest bits in the region being mapped when the `cl::CommandQueue::enqueueMapImage` command has completed.
- The pointer value returned by `cl::CommandQueue::enqueueMapImage` is derived from the `host_ptr` specified when the image object is created.

Mapped image objects are unmapped using `cl::CommandQueue::enqueueUnmapMemObject`. This is described in the following text.

```cpp
cl_int cl::CommandQueue::enqueueUnmapMemObject(
    const Memory& memory,
    void * mapped_ptr,
    const VECTOR_CLASS<Event> * events = NULL,
    Event * event = NULL)
```

enqueues a command to unmapped a previously mapped region of a memory object. Reads or writes from the host using the pointer returned by `cl::CommandQueue::enqueueMapBuffer`, or `cl::CommandQueue::enqueueMapImage` are considered to be complete.
memobj is a valid memory object. The OpenCL context associated with command_queue and memobj must be the same.

mapped_ptr is the host address returned by a previous call to cl::CommandQueue::enqueueMapBuffer, or cl::CommandQueue::enqueueMapImage for memobj.

events specifies events that need to complete before this particular command can be executed. If events is NULL or of length zero, then this particular command does not wait on any event to complete. If events is not NULL and a nonzero length, the list of events pointed to by events must be valid. The events specified in events act as synchronization points. The context associated with events in events and the command-queue must be the same.

event returns an event object that identifies this particular copy command and can be used to query or queue a wait for this particular command to complete. event can be NULL, in which case it will not be possible for the application to query the status of this command or queue a wait for this command to complete. Cl::CommandQueue::enqueueBarrier can be used instead.

Cl::CommandQueue::enqueueUnmapMemObject returns CL_SUCCESS on success. Otherwise it returns one of the following errors:

- CL_INVALID_MEM_OBJECT if memobj is not a valid memory object.
- CL_INVALID_VALUE if mapped_ptr is not a valid pointer returned by cl::CommandQueue::enqueueMapBuffer, or cl::CommandQueue::enqueueMapImage for memobj.
- CL_INVALID_EVENT_WAIT_LIST if event objects in events are not valid events.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.
- CL_INVALID_CONTEXT if context associated with the command queue and memobj are not the same or if the context associated with the command queue and events in events are not the same.

cl::CommandQueue::enqueueMapBuffer, and cl::CommandQueue::enqueueMapImage increments the mapped count of the memory object. The initial mapped count value of the memory object is zero. Multiple calls to cl::CommandQueue::enqueueMapBuffer, or cl::CommandQueue::enqueueMapImage on the same memory object will increment this mapped count by appropriate number of calls.

cl::CommandQueue::enqueueUnmapMemObject decrements the mapped count of the memory object.

cl::CommandQueue::enqueueMapBuffer, and cl::CommandQueue::enqueueMapImage act as synchronization points for a region of the buffer object being mapped.

The method

```c
cl_int cl::CommandQueue::enqueueMarkerWithWaitlist(
    const VECTOR_CLASS<Event> * events = NULL,
    Event * event = NULL)
```

enqueues a marker command that waits for completion of a list of events.
events specifies a list of events. If NULL, the marker command waits for the completion of all previously
enqueued commands.

event returns an event object that identifies this command. It can be used to query or queue a wait for this
particular command to complete. event can be NULL, in which case it will not be possible for the application to
query the status of this command or queue a wait for this command to complete.

cl::CommandQueue::enqueueMarkerWithWaitlist returns CL_SUCCESS on success.

The method

    cl_int cl::CommandQueue::enqueueBarrierWithWaitlist(
        const VECTOR_CLASS<Event> * events = NULL,
        Event * event = NULL)

enqueues a barrier command that waits for completion of a list of events.

events specifies a list of events. If NULL, the barrier command waits for the completion of all previously
enqueued commands.

event returns an event object that identifies this command. It can be used to query or queue a wait for this
particular command to complete. event can be NULL, in which case it will not be possible for the application to
query the status of this command or queue a wait for this command to complete.

cl::CommandQueue::enqueueBarrierWithWaitlist returns CL_SUCCESS on success.

The method

    cl_int cl::CommandQueue::enqueueMigrateMemObjects(
        const VECTOR_CLASS<Memory> &memObjects,
        cl_mem_migration_flags flags,
        const VECTOR_CLASS<Event> * events = NULL,
        Event * event = NULL)

enqueues a command indicating with which device a set a memory objects should be associated.

memObjects specifies a set of memory objects.

flags specifies migration flags, as in table 5.10 of the OpenCl Specification Version 1.2.

events specifies a list of events on which the command waits. If NULL, the command waits for the completion
of all previously enqueued commands.

event returns an event object that identifies this command. It can be used to query or queue a wait for this
particular command to complete. event can be NULL, in which case it will not be possible for the application to
query the status of this command or queue a wait for this command to complete.

cl::CommandQueue::enqueueMigrateMemObjects returns CL_SUCCESS on success.

The method
cl_int cl::CommandQueue::enqueueNDRangeKernel(
    const Kernel& kernel,
    const NDRange& offset,
    const NDRange& global,
    const NDRange& local,
    const VECTOR_CLASS<Event> * events = NULL,
    Event * event = NULL)

enqueues a command to execute a kernel on a device.

*kernel* is a valid kernel object. The OpenCL context associated with *kernel* and the *command queue* must be the same.

*offset* can be used to specify an array of *work_dim* unsigned values that describe the offset used to calculate the global ID of a work-item. If *offset* is cl::NULLRange, the global IDs start at offset (0, 0, … 0).

*global* points to an array of *work_dim* unsigned values that describe the number of global work-items in *work_dim* dimensions that will execute the kernel function. The total number of global work-items is computed as \( \text{global}[0] \times \ldots \times \text{global}[\text{work_dim} - 1] \).

*local* points to an array of *work_dim* unsigned values that describe the number of work-items that make up a work-group (also referred to as the size of the work-group) that will execute the kernel specified by *kernel*. The total number of work-items in a work-group is computed as \( \text{local}[0] \times \ldots \times \text{local}[\text{work_dim} - 1] \). The total number of work-items in the work-group must be less than or equal to the \text{CL\_DEVICE\_MAX\_WORK\_GROUP\_SIZE} value specified in table 4.3 and the number of work-items specified in \text{local}[0], \ldots \text{local}[\text{work_dim} - 1] must be less than or equal to the corresponding values specified by \text{CL\_DEVICE\_MAX\_WORK\_ITEM\_SIZES}[0], \ldots \text{CL\_DEVICE\_MAX\_WORK\_ITEM\_SIZES}[\text{work_dim} - 1]. The explicitly specified *local* determines how to break the global work-items specified by *global* into appropriate work-group instances. If *local* is specified, the values specified in \text{global}[0], \ldots \text{global}[\text{work_dim} - 1] must be evenly divisible by the corresponding values specified in \text{local}[0], \ldots \text{local}[\text{work_dim} - 1].

The work-group size to be used for *kernel* can also be specified in the program source using the __attribute__((reqd_work_group_size(X, Y, Z))) qualifier (refer to section 6.8.2). In this case the size of work group specified by *local* must match the value specified by the reqd_work_group_size attribute qualifier.

*local* can also be a cl::NULLRange value in which case the OpenCL implementation will determine how to be break the global work-items into appropriate work-group instances.

These work-group instances are executed in parallel across multiple compute units or concurrently on the same compute unit.

Each work-item is uniquely identified by a global identifier. The global ID, which can be read inside the kernel, is computed using the value given by \text{global\_work\_size} and \text{global\_work\_offset}. In addition, a work-item is also identified within a work-group by a unique local ID. The local ID, which can also be read by the kernel, is computed using the value given by \text{local\_work\_size}. The starting local ID is always (0, 0, … 0).

*events* specifies events that need to complete before this particular command can be executed. If *events* is NULL or of length zero, then this particular command does not wait on any event to complete. If *events* is not...
NULL and a nonzero length, the list of events pointed to by `events` must be valid. The events specified in `events` act as synchronization points. The context associated with events in `events` and the command queue must be the same.

`event` returns an event object that identifies this particular copy command and can be used to query or queue a wait for this particular command to complete. `event` can be NULL, in which case it will not be possible for the application to query the status of this command or queue a wait for this command to complete. `cl::CommandQueue::enqueueBarrier` can be used instead.

`cl::CommandQueue::enqueueNDRangeKernel` returns CL_SUCCESS if the kernel execution was successfully queued. Otherwise, it returns one of the following errors:

- CL_INVALID_PROGRAM_EXECUTABLE if there is no successfully built program executable available for device associated with the `command queue`.
- CL_INVALID_KERNEL if `kernel` is not a valid kernel object.
- CL_INVALID_CONTEXT if context associated with the `command queue` and `kernel` are not the same or if the context associated with the `command queue` and events in `events` are not the same.
- CL_INVALID_KERNEL_ARGS if the kernel argument values have not been specified.
- CL_INVALID_GLOBAL_WORK_SIZE if `global` is cl::NULLRange, or if any of the values specified in `global [0]`, … `global [work_dim – 1]` are 0 or exceed the range given by the sizeof(size_t) for the device on which the kernel execution is enqueued.
- CL_INVALID_GLOBAL_OFFSET if the value specified in `global` + the corresponding values in `global` for any dimensions is greater than the sizeof(size t) for the device on which the kernel execution is enqueued.
- CL_INVALID_WORK_GROUP_SIZE if `local` is specified and number of work-items specified by `global` is not evenly divisible by size of work-group given by `local` or does not match the work-group size specified for `kernel` using the __attribute__((reqd_work_group_size(X, Y, Z))) qualifier in program source.
- CL_INVALID_WORK_GROUP_SIZE if `local` is specified and the total number of work-items in the work-group computed as `local [0] * … local [work_dim – 1]` is greater than the value specified by CL_DEVICE_MAX_WORK_GROUP_SIZE in table 4.3.
- CL_INVALID_WORK_GROUP_SIZE if `local` is NULL and the __attribute__((reqd_work_group_size(X, Y, Z))) qualifier declares the work-group size for `kernel` in the program source.
- CL_INVALID_WORK_ITEM_SIZE if the number of work-items specified in any of `local [0]`, … `local [work_dim – 1]` is greater than the corresponding values specified by CL_DEVICE_MAX_WORK_ITEM_SIZES[0], … CL_DEVICE_MAX_WORK_ITEM_SIZES[work_dim – 1].
- CL_MISALIGNED_SUB_BUFFER_OFFSET if a sub-buffer object is specified as the value for an argument that is a buffer object and the offset specified when the sub-buffer object is created is not aligned to CL_DEVICE_MEM_BASE_ADDR_ALIGN value for device associated with queue.

- CL_INVALID_IMAGE_SIZE if an image object is specified as an argument value and the image dimensions (image width, height, specified or compute row and/or slice pitch) are not supported by device associated with queue.

- CL_OUT_OF_RESOURCES if there is a failure to queue the execution instance of kernel on the command-queue because of insufficient resources needed to execute the kernel. For example, the explicitly specified local causes a failure to execute the kernel because of insufficient resources such as registers or local memory. Another example would be the number of read-only image args used in kernel exceed the CL_DEVICE_MAX_READ_IMAGE_ARGS value for device or the number of write-only image args used in kernel exceed the CL_DEVICE_MAX_WRITE_IMAGE_ARGS value for device or the number of samplers used in kernel exceed CL_DEVICE_MAX_SAMPLERS for device.

- CL_MEM_OBJECT_ALLOCATION_FAILURE if there is a failure to allocate memory for data store associated with image or buffer objects specified as arguments to kernel.

- CL_INVALID_EVENT_WAIT_LIST if event objects in events are not valid events.

- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The method

```cpp
cl_int cl::CommandQueue::enqueueTask(
    const Kernel& kernel,
    const VECTOR_CLASS<Event> * events = NULL,
    Event * event = NULL)
```

enqueues a command to execute a kernel on a device. The kernel is executed using a single work-item.

kernel is a valid kernel object. The OpenCL context associated with kernel and command-queue must be the same.

events specifies events that need to complete before this particular command can be executed. If events is NULL or of length zero, then this particular command does not wait on any event to complete. If events is not NULL and a nonzero length, the list of events pointed to by events must be valid. The events specified in events act as synchronization points. The context associated with events in events and the command queue must be the same.

event returns an event object that identifies this particular copy command and can be used to query or queue a wait for this particular command to complete. event can be NULL, in which case it will not be possible for the application to query the status of this command or queue a wait for this command to complete. cl::CommandQueue::enqueueBarrier can be used instead.
cl::CommandQueue::EnqueueTask is equivalent to calling cl::CommandQueue::enqueueNDRangeKernel with \( work\_dim = 1, global = \text{NULLRange}, global [0] \) set to 1 and \( local [0] \) set to 1.

Cl::CommandQueue::enqueueTask returns CL_SUCCESS if the kernel execution was successfully queued. Otherwise, it returns one of the following errors:

- CL_INVALID_PROGRAM_EXECUTABLE if there is no successfully built program executable available for device associated with the command queue.
- CL_INVALID_KERNEL if kernel is not a valid kernel object.
- CL_INVALID_CONTEXT if context associated with the command queue and kernel are not the same or if the context associated with the command queue and events in events are not the same.
- CL_INVALID_KERNEL_ARGS if the kernel argument values have not been specified.
- CL_INVALID_WORK_GROUP_SIZE if a work-group size is specified for kernel using the \( \_\_\text{attribute\_\_}((\text{reqd\_\_work\_\_group\_\_size(X, Y, Z))) \) qualifier in program source and is not \( (1, 1, 1) \).
- CL_MISALIGNED_SUB_BUFFER_OFFSET if a sub-buffer object is specified as the value for an argument that is a buffer object and the offset specified when the sub-buffer object is created is not aligned to CL_DEVICE_MEM_BASE_ADDR_ALIGN value for device associated with queue.
- CL_INVALID_IMAGE_SIZE if an image object is specified as an argument value and the image dimensions (image width, height, specified or compute row and/or slice pitch) are not supported by device associated with queue.
- CL_OUT_OF_RESOURCES if there is a failure to queue the execution instance of kernel on the command-queue because of insufficient resources needed to execute the kernel.
- CL_MEM_OBJECT_ALLOCATION_FAILURE if there is a failure to allocate memory for data store associated with image or buffer objects specified as arguments to kernel.
- CL_INVALID_EVENT_WAIT_LIST if event objects in events are not valid events.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The method

```c
cl_int cl::CommandQueue::enqueueNativeKernel(
    void (*user_func) (void *),
    std::pair<void*, ::size_t> args,
    const VECTOR_CLASS<Memory> * mem_objects = NULL,
    const VECTOR_CLASS<const void *> * mem_locs = NULL,
    const VECTOR_CLASS<Event> * events = NULL,
    Event * event = NULL)
```

enqueues a command to execute a native C/C++ function not compiled using the OpenCL compiler.

A native user function can only be executed on a command queue created on a device that has CL_EXEC_NATIVE_KERNEL capability set in CL_DEVICE_EXECUTION_CAPABILITIES as specified in table 4.3.

`user_func` is a pointer to a host-callable user function.
args is a tuple containing a pointer to the args list that user_func should be called with and the is the size in bytes of the argument list that args points to.

The data pointed to by args.fst and args.snd bytes in size is copied and a pointer to this copied region is passed to user_func. The copy needs to be done because the memory objects (cl_mem values) that args may contain need to be modified and replaced by appropriate pointers to global memory. When cl::CommandQueue::enqueueNativeKernel returns, the memory region pointed to by args can be reused by the application.

mem_objects is a list of valid buffer objects. The buffer object values specified in mem_objects are memory objects (cl::Memory values) returned by cl::Buffer.

mem_loc is a vector of appropriate locations that args points to where memory objects (cl::Memory values) are stored. Before the user function is executed, the memory object handles are replaced by pointers to global memory.

events specifies events that need to complete before this particular command can be executed. If events is NULL or of length zero, then this particular command does not wait on any event to complete. If events is not NULL and a nonzero length, the list of events pointed to by events must be valid. The events specified in events act as synchronization points. The context associated with events in events and the command queue must be the same.

event returns an event object that identifies this particular copy command and can be used to query or queue a wait for this particular command to complete. event can be NULL, in which case it will not be possible for the application to query the status of this command or queue a wait for this command to complete. cl::CommandQueue::enqueueBarrier can be used instead.

Cl::CommandQueue::enqueueNativeKernel returns CL_SUCCESS if the user function execution instance was successfully queued. Otherwise, it returns one of the following errors:

- CL_INVALID_CONTEXT if context associated with the command queue and events in events are not the same.
- CL_INVALID_VALUE if user_func is NULL.
- CL_INVALID_VALUE if args.fst is a NULL value and args.snd > 0, or if args.fst is a NULL value and then length of mem_objects > 0.
- CL_INVALID_VALUE if args.fst is not NULL and args.snd is 0.
- CL_INVALID_VALUE if the length of mem_objects > 0 and mem_locs is NULL.
- CL_INVALID_VALUE if length of mem_objects is 0 and mem_locs is not NULL.
- CL_INVALID_OPERATION if device cannot execute the native kernel.
- CL_INVALID_MEM_OBJECT if one or more memory objects specified in mem_objects are not valid or are not buffer objects.
- CL_OUT_OF_RESOURCES if there is a failure to queue the execution instance of kernel on the command-queue because of insufficient resources needed to execute the kernel.
- CL_MEM_OBJECT_ALLOCATION_FAILURE if there is a failure to allocate memory for data store associated with buffer objects specified as arguments to kernel.
- CL_INVALID_EVENT_WAIT_LIST if event objects in events are not valid events.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.
The method

```cpp
cl_int cl::CommandQueue::enqueueMarker(Event * event = NULL)
```

enqueues a marker command to the command queue. The command returns an `event` which can be used to queue a wait on this marker (i.e., to wait for all commands queued before the marker to complete).

**cl::CommandQueue::enqueueMarker** returns CL_SUCCESS if the function is successfully executed. Otherwise, it returns one of the following errors:

- CL_INVALID_VALUE if `event` is a NULL value.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The method

```cpp
cl_int cl::CommandQueue::enqueueWaitForEvents(
    const VECTOR_CLASS<Event>& events)
```

enqueues a wait for a specific event or a list of events to complete before any future commands queued in the command queue are executed. Each event in `events` must be a valid event object returned by a previous call to **cl::CommandQueue::enqueueNDRangeKernel**, **cl::CommandQueue::enqueueTask**, **cl::CommandQueue::enqueueNativeKernel**, **cl::CommandQueue::enqueue{Read|Write|Map}{Buffer|Image}**, **cl::CommandQueue::enqueue{Read|Write}BufferRect**, **cl::CommandQueue::enqueueCopy{Buffer|Image}**, **cl::CommandQueue::enqueueCopyBufferRect**, **cl::CommandQueue::enqueueCopyBufferToImage**, **cl::CommandQueue::enqueueCopyImageToBuffer**, or **cl::CommandQueue::enqueueMarker**.

The events specified in `events` act as synchronization points. The context associated with events in `events` and then command queue must be the same.

**cl::CommandQueue::enqueueWaitForEvents** returns CL_SUCCESS if the function was successfully executed. Otherwise, it returns one of the following errors:

- CL_INVALID_CONTEXT if the context associated with `command_queue` and events in `event_list` are not the same.
- CL_INVALID_VALUE if the length of `events` is 0.
- CL_INVALID_EVENT if event objects specified in `events` are not valid events.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The method

```cpp
cl_int cl::CommandQueue::enqueueAcquireGLObjects(
    const VECTOR_CLASS<Memory>* mem_objects = NULL,
    const VECTOR_CLASS<Event> * events = NULL,
```
Event * event = NULL)

enqueues a command to acquire OpenCL memory objects created from OpenGL objects.

*mem_objects* is the list of OpenCL memory objects that correspond to OpenGL objects.

*events* specifies a list of events on which the command waits. If NULL, the command waits for the completion of all previously enqueued commands.

*event* returns an event object that identifies this command. It can be used to query or queue a wait for this particular command to complete. *event* can be NULL, in which case it will not be possible for the application to query the status of this command or queue a wait for this command to complete.

**cl::CommandQueue::enqueueAcquireGLObjects** returns CL_SUCCESS on success.

The method

```
cl_int cl::CommandQueue::enqueueReleaseGLObjects(
    const VECTOR_CLASS<Memory>* mem_objects = NULL,
    const VECTOR_CLASS<Event> * events = NULL,
    Event * event = NULL)
```

enqueues a command to release OpenCL memory objects created from OpenGL objects.

*mem_objects* is the list of OpenCL memory objects that correspond to OpenGL objects.

*events* specifies a list of events on which the command waits. If NULL, the command waits for the completion of all previously enqueued commands.

*event* returns an event object that identifies this command. It can be used to query or queue a wait for this particular command to complete. *event* can be NULL, in which case it will not be possible for the application to query the status of this command or queue a wait for this command to complete.

**cl::CommandQueue::enqueueReleaseGLObjects** returns CL_SUCCESS on success.

The method

```
cl_int cl::CommandQueue::enqueueBarrier(void)
```

enqueues a barrier operation. The **cl::CommandQueue::enqueueBarrier** command ensures that all queued commands in *command_queue* have finished execution before the next batch of commands can begin execution. The **cl::CommandQueue::enqueueBarrier** command is a synchronization point.

**Cl::CommandQueue::enqueueBarrier** returns CL_SUCCESS if the function was executed successfully. It returns CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The method

```
cl_int cl::CommandQueue::flush(void)
```
issues all previously queued OpenCL commands in the *command queue* to the device. 

**Cl::CommandQueue::flush** only guarantees that all queued commands to *command queue* get issued to the appropriate device. There is no guarantee that they will be complete after **Cl::CommandQueue::flush** returns.

**Cl::CommandQueue::flush** returns CL_SUCCESS if the function call was executed successfully. Otherwise it returns CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The method

```cpp
cl_int cl::CommandQueue::finish(void)
```

blocks until all previously queued OpenCL commands in the *command queue* are issued to the associated device and have completed. **Cl::CommandQueue::finish** does not return until all queued commands in the *command queue* have been processed and completed. **Cl::CommandQueue::finish** is also a synchronization point.

**cl::CommandQueue::Finish** returns CL_SUCCESS if the function call was executed successfully. Otherwise it returns CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 4. Exceptions

The use of C++ exceptions can provide a structured approach to error handling for large applications. The C++ API provides the ability to use C++ exceptions to track and handle errors generated by the underlying OpenCL C API. However, the use of C++ exceptions is not universal and their use should be optional. In the case that exceptions are not used, the resulting application must compile and work without exception support.

By default, C++ exceptions are not enabled and the OpenCL error code is returned, or set, as per the underlying C API. To enable the use of exceptions, the user must explicitly define preprocessor macro:

```cpp
__CL_ENABLE_EXCEPTIONS
```

Once enabled, an error (i.e., a value other than CL_SUCCESS) originally reported via return value instead will be reported by throwing an exception of class **cl::Error**. By default, the method **cl::Error::what()** returns a const pointer to a string naming the particular C API call that reported the error (e.g., "clGetDeviceInfo", "clGetPlatformInfo", and so on).

To override the default behavior for **cl::Error::what()**, define the preprocessor macro:

```cpp
__CL_USER_OVERRIDE_ERROR_STRINGS
```

and provide string constants for each preprocessor macro defined in Table 11. Most macros apply to both OpenCL 1.1 and OpenCL 1.2; these have a blank Version column in the table. Macros marked V1.2 in the
Version column are defined for OpenCL 1.2 only. Macros marked V1.1 in the Version column are defined for OpenCL 1.1 only; the corresponding OpenCL APIs are deprecated, and the user must define

```
__CL_USE_DEPRECATED_OPENCL_1_1_APIS
```

to use these V1.1 macros.

<table>
<thead>
<tr>
<th>Preprocessor macro name</th>
<th>Default value</th>
<th>Version</th>
</tr>
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<td>__COMPILE_PROGRAM_ERR</td>
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Table 13: Preprocessor error macros and their defaults.
5. Using the C++ API with Standard Template Library

The C++ Standard Template Library is an excellent resource for quick access to many useful algorithms and containers, but it is often not used due to compatibility issues across different toolchains and operating systems, among other reasons. The OpenCL C++ wrapper API uses vectors and strings in a number of places. By default, it uses Standard Template Library vector and string classes `std::vector` and `std::string`. However, it also gives the developer the ability to not use these.

The C++ wrapper API provides replacements `cl::vector` for `std::vector` and `cl::string` for `std::string`. It also allows developers to use their own implementations instead.

By default, to avoid issues with backward compatibility, the C++ wrapper uses both `std::vector` and `std::string`. Either can be overridden, with `cl::vector` and `cl::type`; however, the developer should be aware that these types are deprecated. For vectors, the developer can select an alternative version by defining the preprocessor macro:

`__NO_STD_VECTOR`

In this case, the following vector type is defined:

```
template cl::vector<typename T,
    unsigned int N = __MAX_DEFAULT_VECTOR_SIZE>
```

`cl::vector` shares the same interface as `std::vector`, but it has a statically defined space requirement, by default 10 elements. The developer can manually override this allocation by defining the preprocessor macro:

`__MAX_DEFAULT_VECTOR_SIZE N`

where `N` is the number of vector elements to use when allocating values of type `cl::vector`.

By defining the preprocessor macro:

`__USE_DEV_VECTOR`

neither `std::vector` nor `cl::vector` classes will be used. Instead, the user must provide the preprocessor definition:

`VECTOR_CLASS typeName`

where `typeName` corresponds to the user’s vector class\(^4\), with an implementation that matches the `std::vector` interface.

For strings, if the preprocessor macro:

```
__USE_DEV_STRING
```

\(^4\) C++ does not currently support typedef templates and thus the vector type must be given by its name only through the preprocessor macro `VECTOR_CLASS`. 
__NO_STD_STRING

is defined, then the string type `cl::string` is used instead of `std::string`. Unlike `cl::vector`, the size of a given string is not defined statically but is allocated at creation. A developer can provide a replacement implementation for `std::string` by defining the preprocessor macro:

__USE_DEV_STRING

The developer must provide the following typedef:

typedef `stringType` STRING_CLASS

where `stringType` is the user provided alternative for `std::string`, with an implementation that matches the interface for `std::string`. 
6. Index

This index lists each class, constructor, and method defined by the C++ wrapper API. Methods are listed under their fully qualified names; e.g., the many `getInfo` methods are listed under `cl::Context::getInfo`, `cl::Device::getinfo`, etc., not under `getInfo`.

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